



**ESA-MOST Dragon Cooperation**

中国科技部-欧洲空间局“龙计划”合作

# 2017 DRAGON 4 SYMPOSIUM

2017年“龙计划”四期学术研讨会

26-30 June 2017 | Copenhagen, Denmark

2017年6月26-30日, 丹麦 哥本哈根





ESA–MOST Dragon Cooperation  
2017 DRAGON 4 SYMPOSIUM

A3-ID32426: Calibration and Data Quality

# RESEARCH ON CALIBRATION, VALIDATION AND RETRIEVALS ON SATELLITE-BASED MICROWAVE INSTRUMENTS

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# Outline

- Motivation
- Project introduction
- Main research
- Case study
- Summary and further plan
- Acknowledgement

# Motivation

- ❑ Global monitoring of precipitation is important because of its significant human consequences.
- ❑ Satellite-based radiometer is a good way to monitor and retrieve global precipitation.
- ❑ An obvious challenge is that different levels of bias and calibration accuracy for similar sensors can not be avoided.

## Dragon-4 Project

The paper develops a passive sub-millimeter precipitation retrievals algorithm for Microwave Humidity and Temperature Sounder (MWHTS) onboard the Chinese Feng Yun 3C (FY-3C) satellite.

Meanwhile, calibration and validation between similar instruments onboard different satellites are also important to ensure the effectiveness of observations and accuracy of precipitation retrievals.

In the ongoing work, we are going to carry out the calibration and validation among a series of MWHTS on FY-3 satellites.



## 2<sup>nd</sup> Generation of LEO: FY-3



**Microwave instruments on board FY-3A/B/C, including:**

MWTS: MicroWave Temperature Sounder

MWHS: MicroWave Humidity Sounder

MWRI: MicroWave Radiation Imager

**FY-3 Constellation**  
(FY-3A:Morning ,FY-3B:Afternoon)

✓ After FY-3A, FY-3B was successfully launched on Nov. 5, 2010

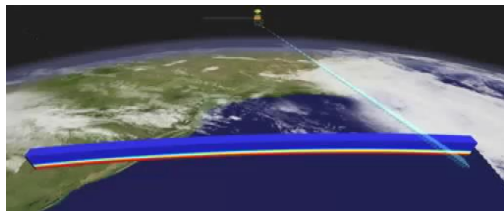
✓ FY-3C was successfully launched on Sept. 23, 2013

No.	Launch	Orbit	Status
FY-3A	May 27,2008	M	Off
FY-3B	Nov 5, 2010	A	On
FY-3C	2013	M	On
FY-3D	2017	A	Op.
FY-3E	2020 (plan)	M	Op.
FY-3G	2023 (plan)	A	Op.
FY-3I	2025 (plan)	M	Op.

## Ongoing progress

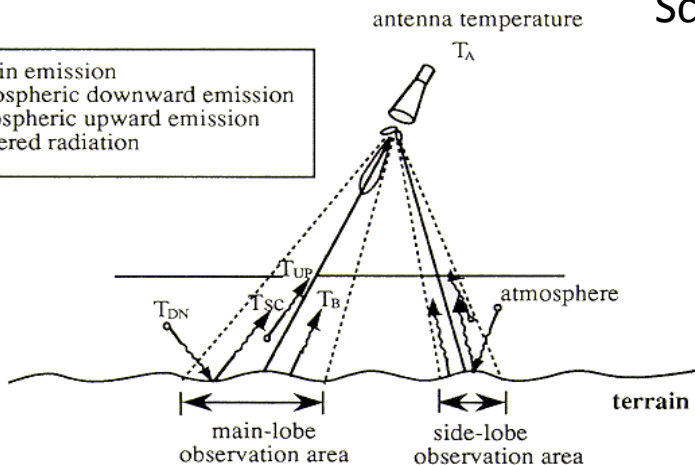
# 1. Instrument: Satellite-based MWHTS/FY-3C

- ◆FY-3C: launched in 23 Sept, 2013.
- ◆MWHTS (mwhs-II): since 2013.9.30



Scanning mode

TB : terrain emission  
TDN: atmospheric downward emission  
TUP: atmospheric upward emission  
TSC: scattered radiation



序号	中心频率 (GHz)	极化	带宽 (MHz)	频率稳定度 (MHz)	动态范围 (K)	灵敏度 (K)	定标精度 (K)	主波束宽度	主波束效率	交叉极化电平
1	89.0	V	1500	50	3-340	1.0	1.3	2.0° ± 0.1°	>92%	≤-17.5dB
2	118.75±0.08	H	20	30	3-340	3.6	2.0	2.0° ± 0.1°	>92%	--
3	118.75±0.2	H	100	30	3-340	2.0	2.0	2.0° ± 0.1°	>92%	--
4	118.75±0.3	H	165	30	3-340	1.6	2.0	2.0° ± 0.1°	>92%	--
5	118.75±0.8	H	200	30	3-340	1.6	2.0	2.0° ± 0.1°	>92%	--
6	118.75±1.1	H	200	30	3-340	1.6	2.0	2.0° ± 0.1°	>92%	--
7	118.75±2.5	H	200	30	3-340	1.6	2.0	2.0° ± 0.1°	>92%	--
8	118.75±3.0	H	1000	30	3-340	1.0	2.0	2.0° ± 0.1°	>92%	--
9	118.75±5.0	H	2000	30	3-340	1.0	2.0	2.0° ± 0.1°	>92%	--
10	150.0	V	1500	50	3-340	1.0	1.3	1.1° ± 0.1°	>95%	≤-17.5dB
11	183.31±1	H	500	30	3-340	1.0	1.3	1.1° ± 0.1°	>95%	--
12	183.31±1.8	H	700	30	3-340	1.0	1.3	1.1° ± 0.1°	>95%	--
13	183.31±3	H	1000	30	3-340	1.0	1.3	1.1° ± 0.1°	>95%	--
14	183.31±4.5	H	2000	30	3-340	1.0	1.3	1.1° ± 0.1°	>95%	--
15	183.31±7	H	2000	30	3-340	1.0	1.3	1.1° ± 0.1°	>95%	--

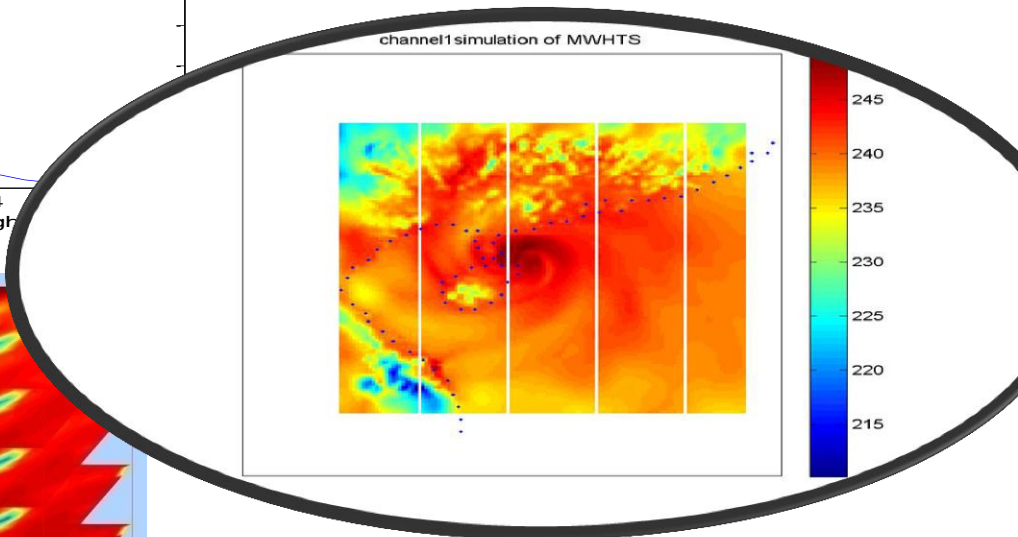
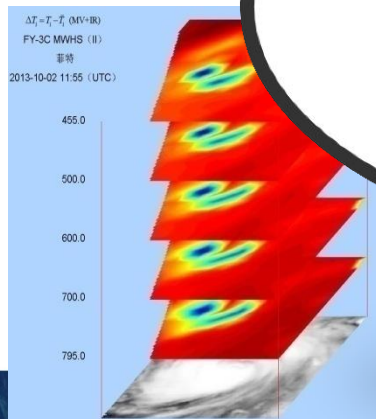
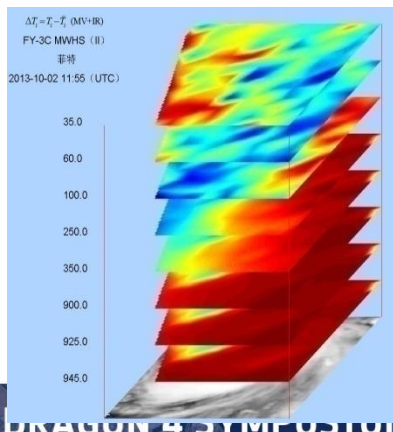
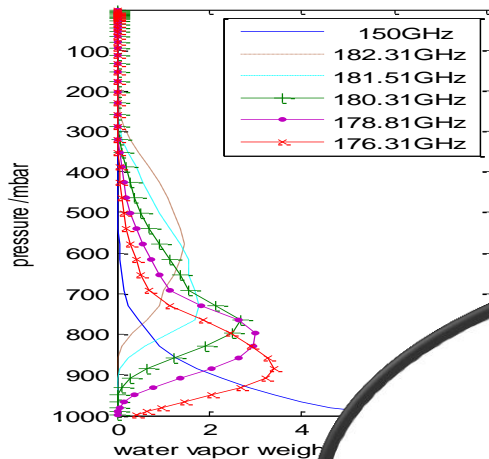
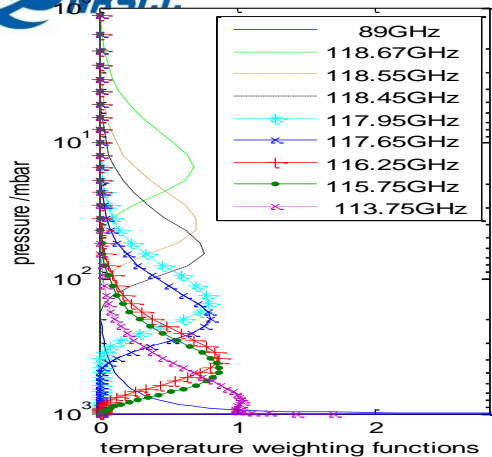
✓ polar-orbiting satellites in [sun-synchronous orbits](#)

✓ approximately 14 orbits

✓ MR: either daylight or nighttime mode

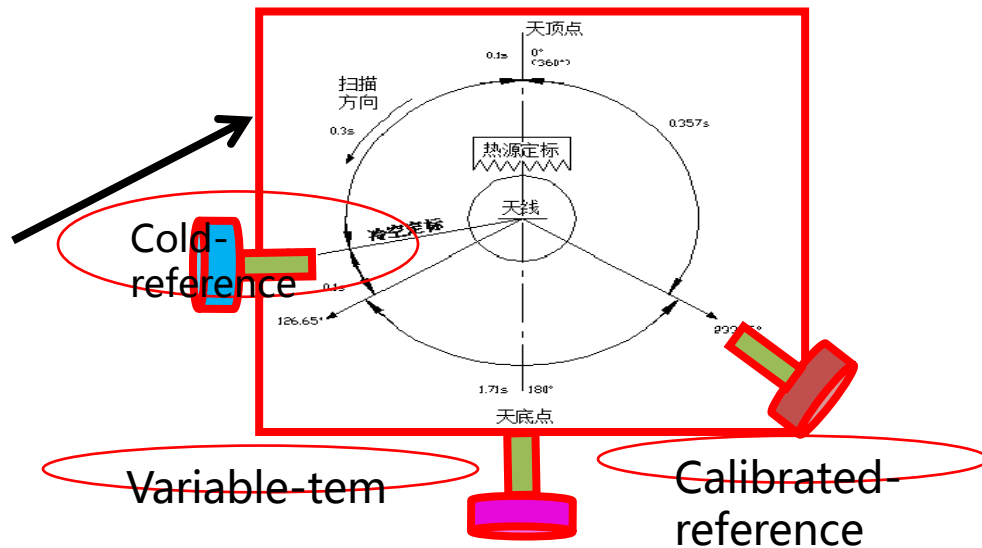
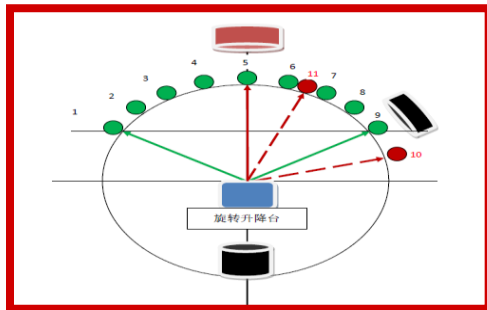
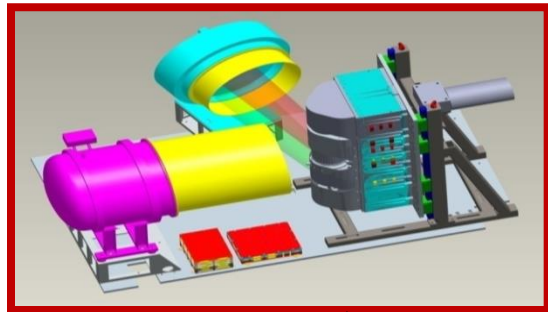
✓ Polar regions are observed nearly every 100





## 2. Calibration and validation

T/V calibration FY-3C----FY-3D-----FY-3(05)



# Matching results for validation

FY-3A

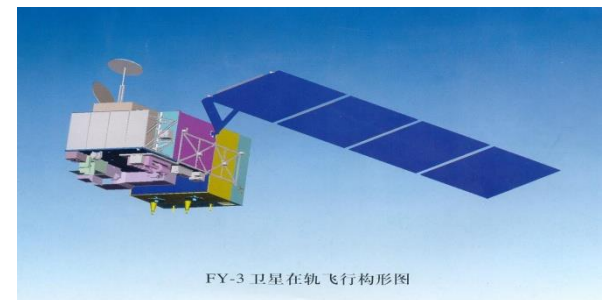
time	satellite	Pass time	Raob
2008/9/9	FY3A	11: 22	10: 50
2008/9/9	AQUA	14: 38	14: 00
2008/9/10	N18	14: 45	14: 15
2008/9/11	N18	14: 34	14: 00
2008/9/12	FY3A	12: 06	11: 30
2008/9/12	N18	3: 07	2: 30

FY-3B

time	satellite	Pass time	Raob	Observing time
2010/11/11	AQUA	3:01	2:30	2:01-4:01
2010/11/12	AQUA	14:39	14:09	12:39-15:39
2010/11/14	NA19	14:28	14:00	12:28-15:28
2010/11/14	NA18	15:27	15:00	13:27-16:27
2010/11/15	NA19	3:01	2: 31	1:01-4:01
2010/11/15	NA18	4:00	3: 30	2:00-5:00
2010/11/15	FY	23:12	22: 42	21:12-00:12

## FY-3C

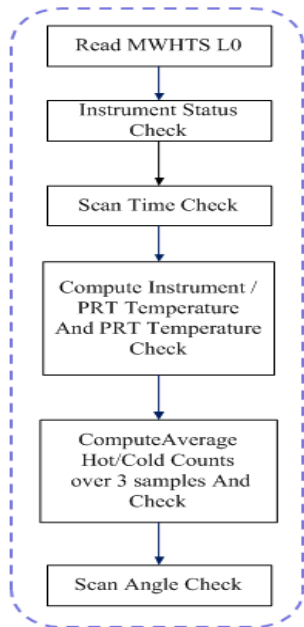
DATE	Sensors	Pass time	Incident angle	Raob
2015-12-01	FY-3C/MWHTS	11:55:10	9.06	11:30
	NPP/ATMS	14:33:40	10.31	15:00
	FY-3B/MWHS	15:29:00	2.29	
2015-12-02	NPP/ATMS	03:02:00	9.05	03:30
	FY-3B/MWHS	03:59:20	3.54	
	Metop-A/MHS	11:13:23	27.71	11:10
	FY-3C/MWHTS	11:36:30	26.83	
	NPP/ATMS	14:15:00	25.38	14:40
	FY-3B/MWHS	15:14:00	26.24	
	Metop-A/MHS	22:25:23	7.89	22:00



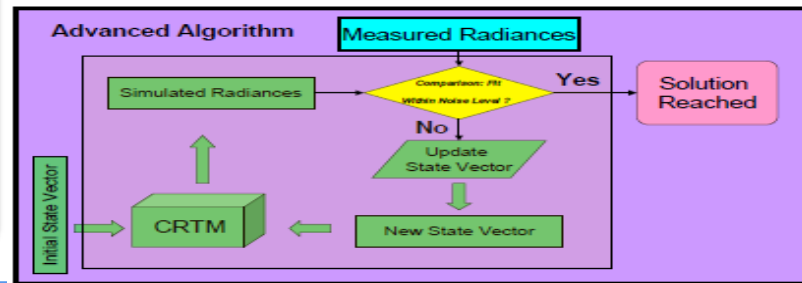
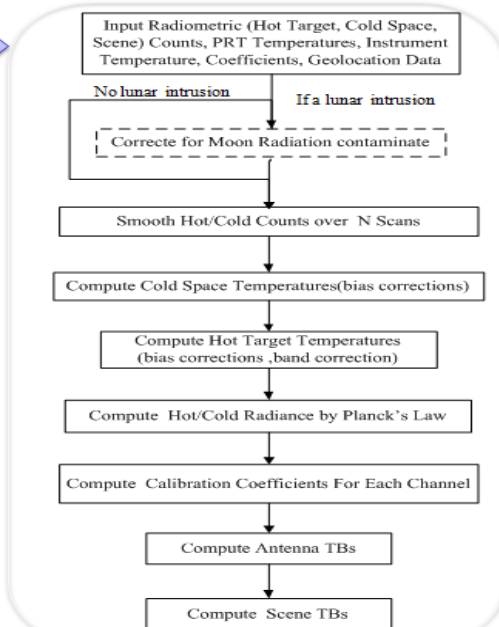


### 3. Quality control

Quality control flow chart



Calibration flow chart



# 4. Atmospheric retrievals

- RT Solutions

$$B(\nu, T) = \frac{2kT\nu^2}{c^2}$$

$$B_a(\nu) = \int_0^\infty \alpha(\nu, z) B[\nu, T(z)] e^{-\tau(\nu, z)} dz$$

$$\tau(\nu, z) = \int_z^\infty \alpha(\nu, \zeta) d\zeta$$

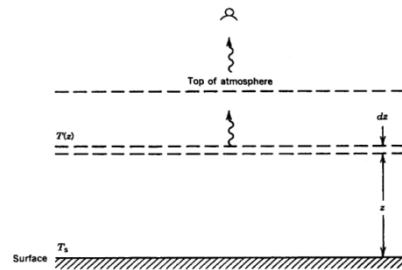
$$T_a(\nu) = \int_0^\infty \alpha(\nu, z) T(z) \exp\left[-\int_z^\infty \alpha(\nu, \zeta) d\zeta\right] dz$$

$$T_a(\nu) = \int_0^\infty W(\nu, z) T(z) dz \quad W(\nu, z) = \alpha(\nu, z) \exp\left[-\int_z^\infty \alpha(\nu, \zeta) d\zeta\right]$$

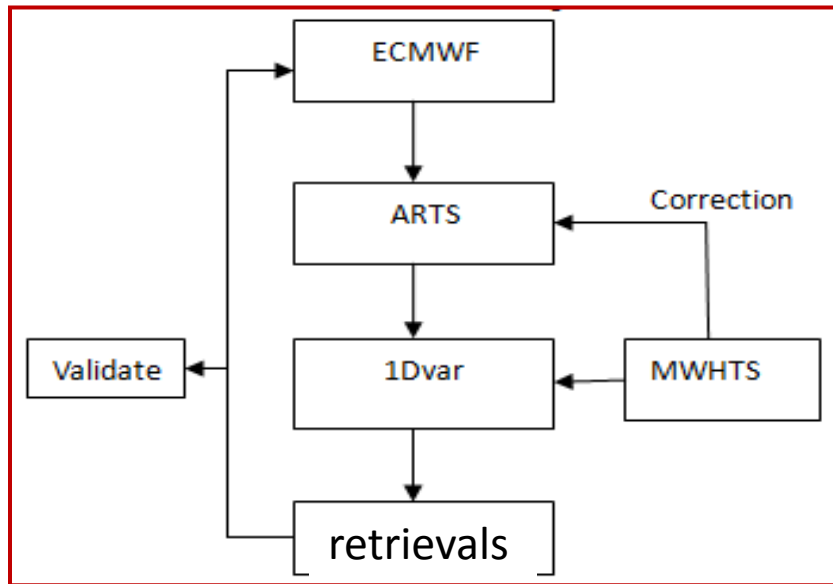
$$T_a(\nu) = \sum_{n=1}^N W(\nu, z_n) T_n \Delta z \quad T_{am} = \sum_{n=1}^N W_{nm} T_n$$

$$\mathbf{T}_a = \mathbf{W} \mathbf{T}$$

$$\mathbf{T} = (\tilde{\mathbf{W}} \mathbf{W})^{-1} \tilde{\mathbf{W}} \mathbf{T}_a$$



# Algorithm and operation steps

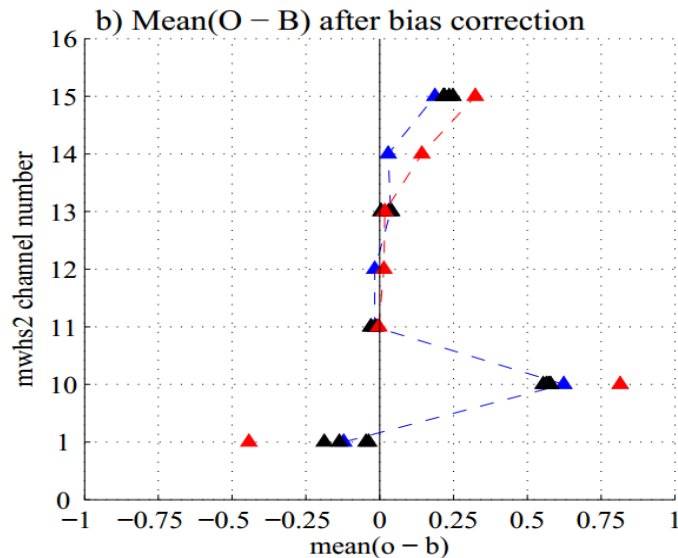


Simulation, retrieval and validation of TPW using

MWHTS onboard FY-3C satellite

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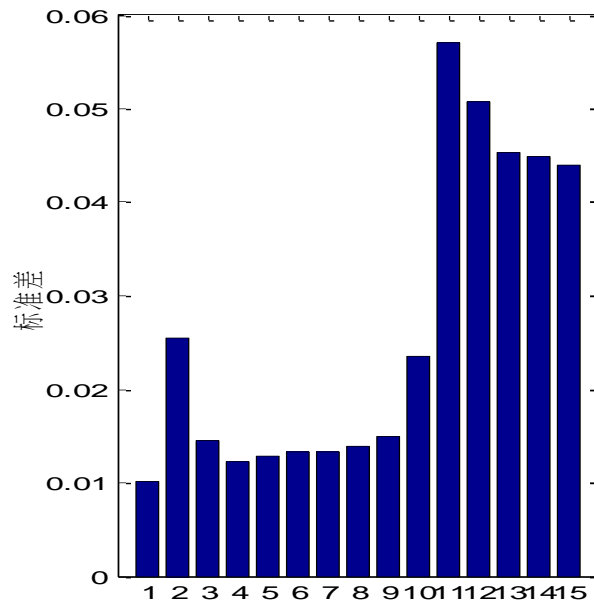
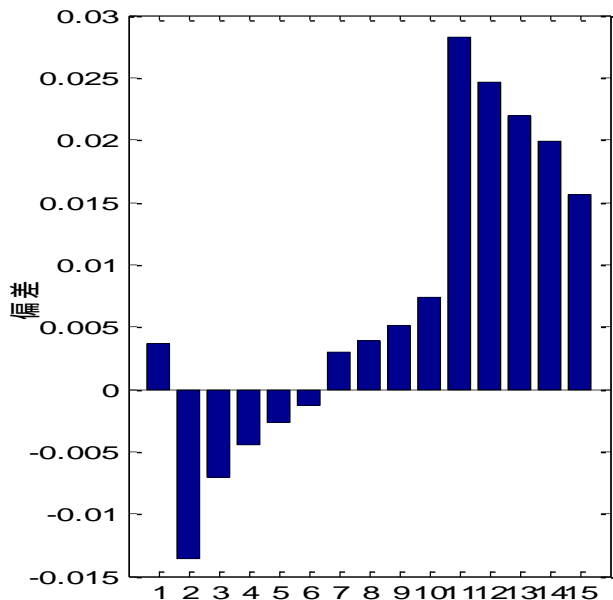
Comparison between ARTS and  
mwhts-II data using radiosondes

(assessment from ECMWF also)

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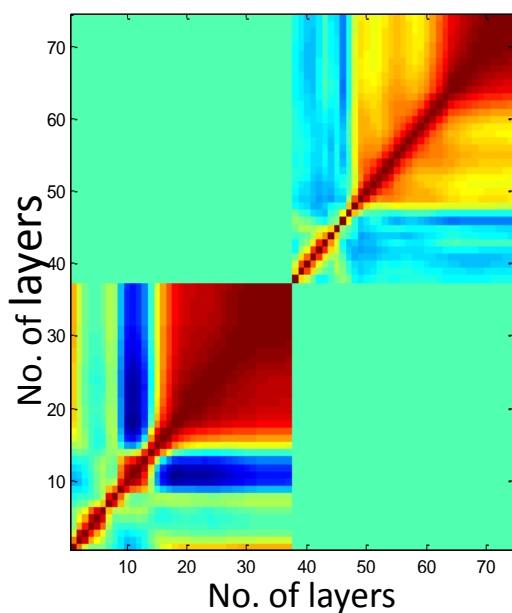
2017年6月26-30日, 丹麦 哥本哈根

# Bias and standard deviation between model and observations

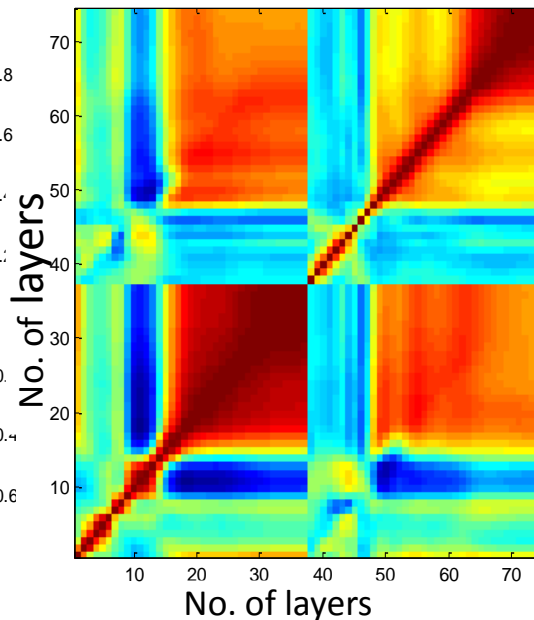




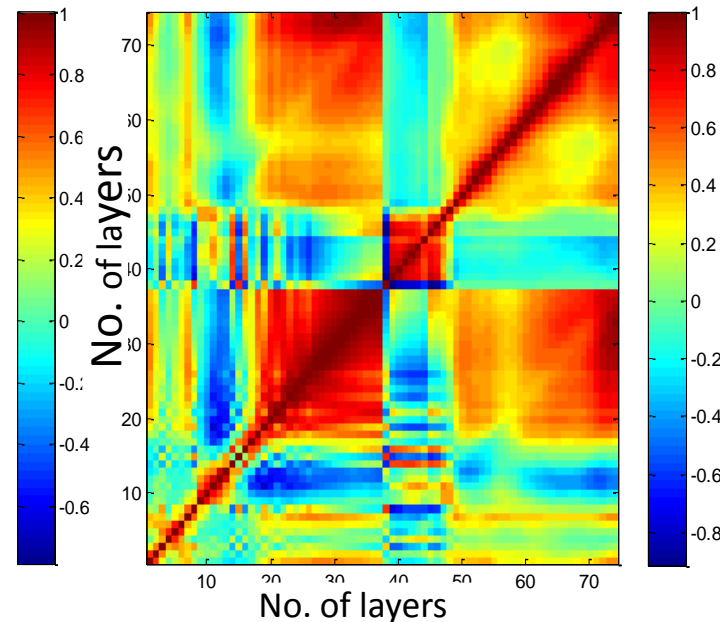
# Correlation coefficient matrix



Single Correlation matrix

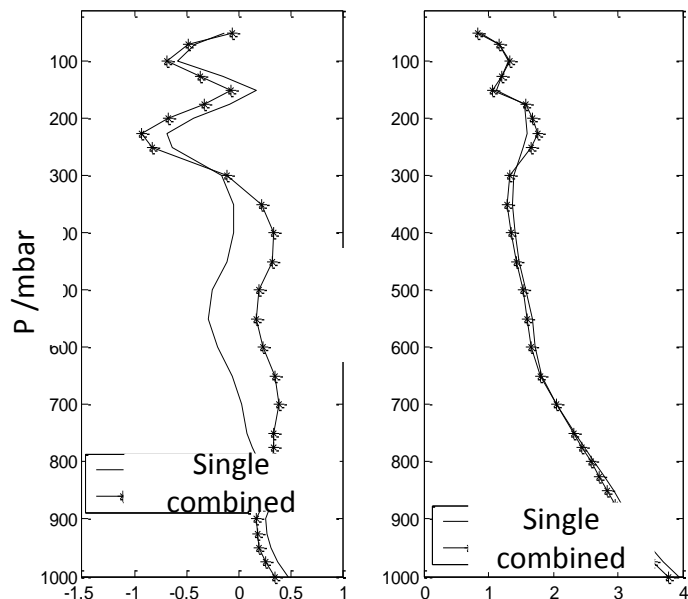


Combined Correlation matrix

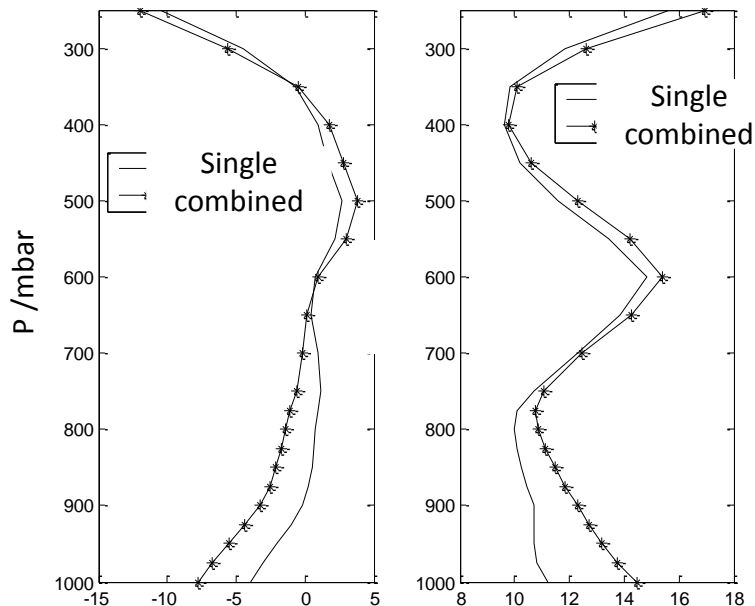


Combined Correlation matrix  
mixing ratio partial density

# Role of background error covariance

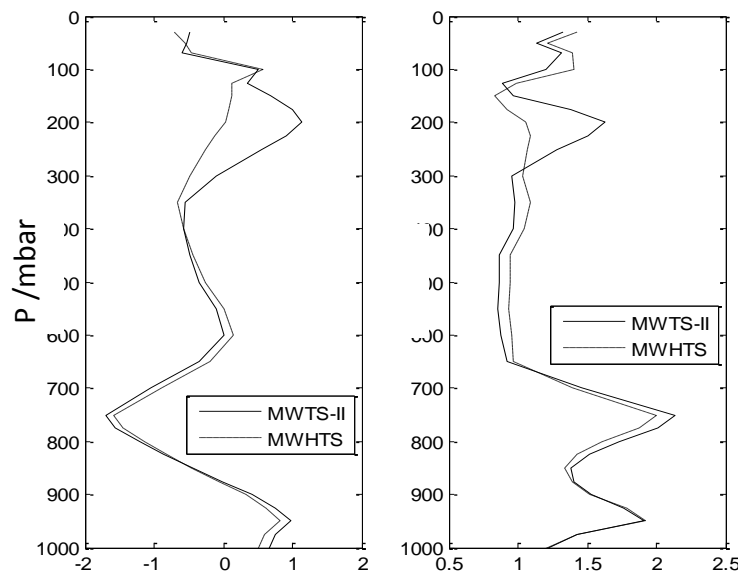
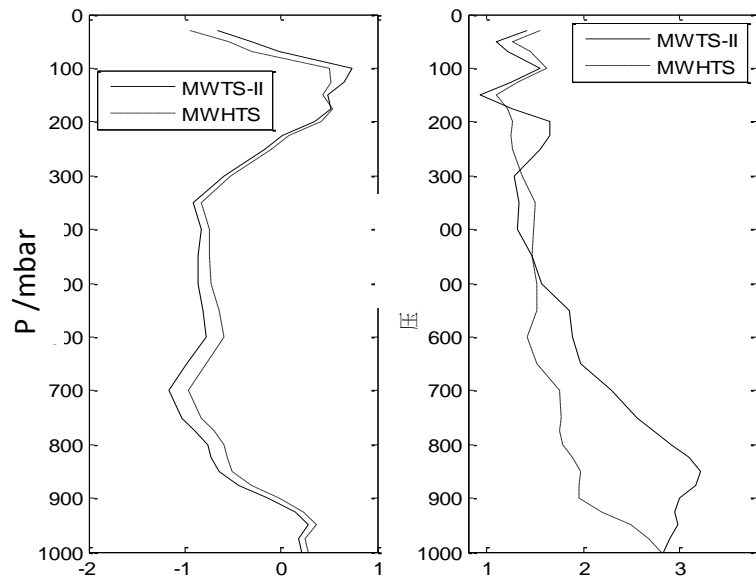


Bias and RMS of  
temperature retrievals



Bias and RMS of RH  
retrievals

## 5. Results of retrievals



## 6. Focus on extreme situations (urgent)



## Case study for hurricane Hermine(2016)

Domain 1: -75 to -35 lon, 20 to 42 lat

Domain 2: -65 to -43 lon ; 22 to 40 lat

time\_step=90

interval time: 60, 15mins

frames per outfile: 1000

mp\_physics=6 (includes 6 water particles)

mp\_physics=3 (old version)

Atmospheric state:

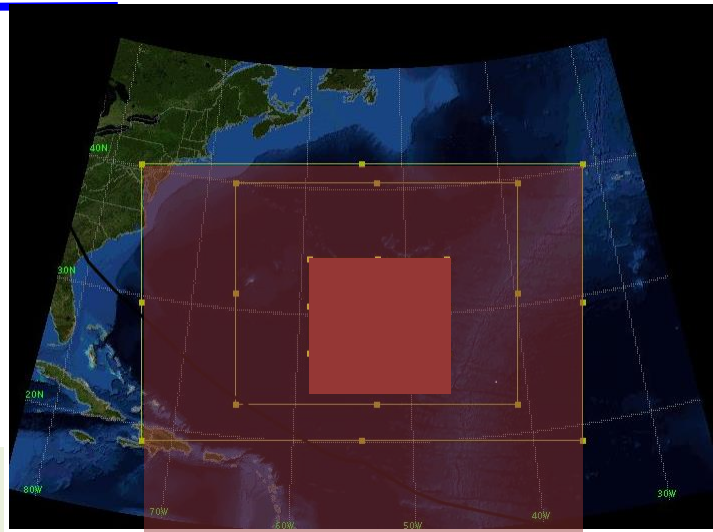
Vars: H, P, T, ROv, ROcloud, ROrain, ROice,  
ROsnow, ROgraup)

Level: 33 with surface

Time interval: 15mins,

Spatial: 5km

Frame: 48



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Domain 1: -75 to -35 lon, 20 to 42 lat

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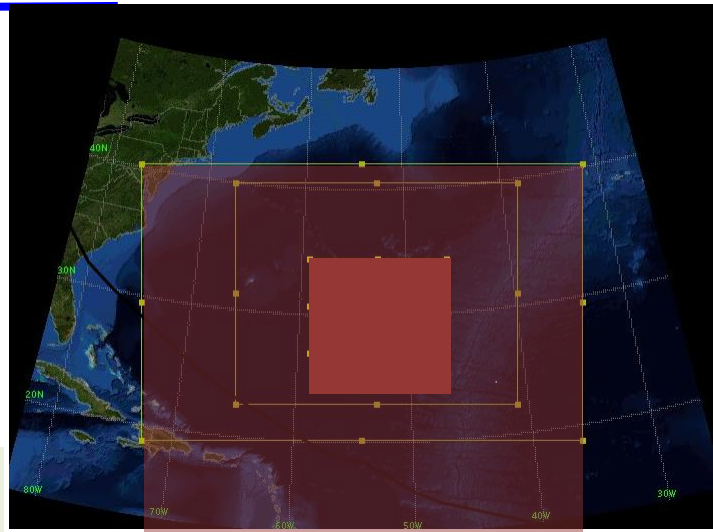
Vars: H, P, T, ROv, ROcloud, ROrain, ROice,  
ROsnow, ROgraup)

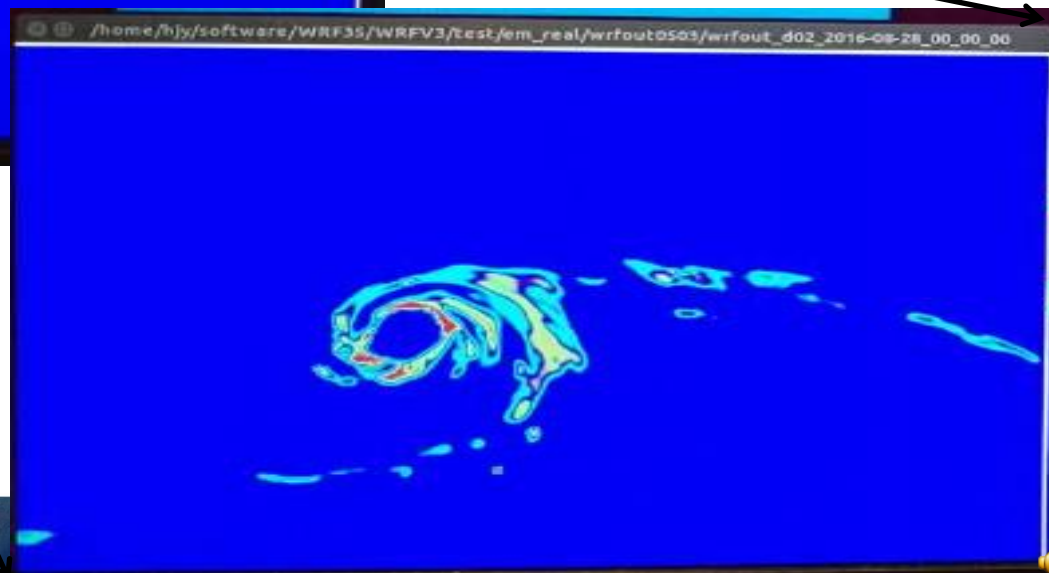
Level: 33 with surface

Time interval: 15mins,

Spatial: 5km

Frame: 48

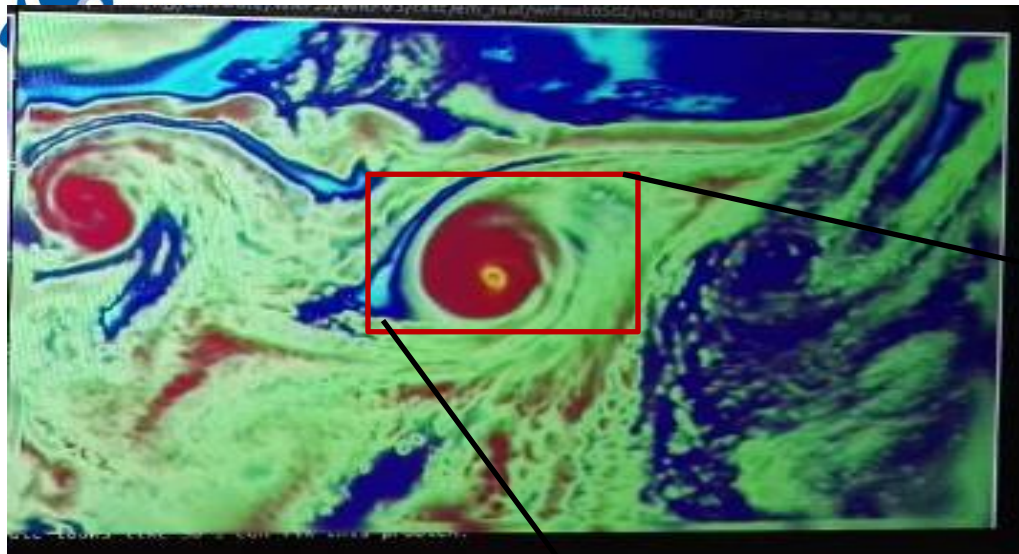




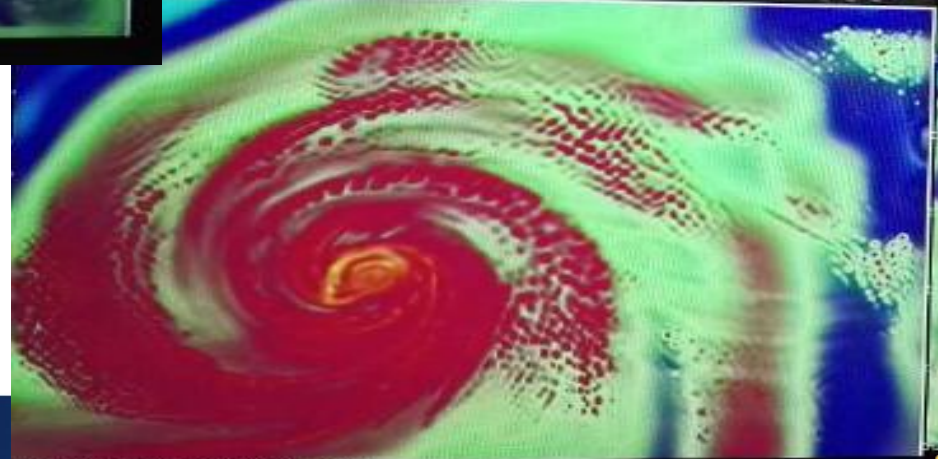
qice

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led in the coordinates attribute  
now what your coordinates attribute  
/software/WRF35/WRFV3/test/em\_real/wrfout20203/wrfout\_d01\_2015-09-28\_00\_00\_00



qvapor

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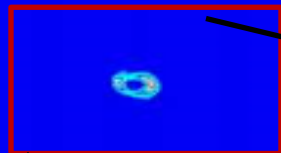
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countered on variable "SS1\_INPUT"

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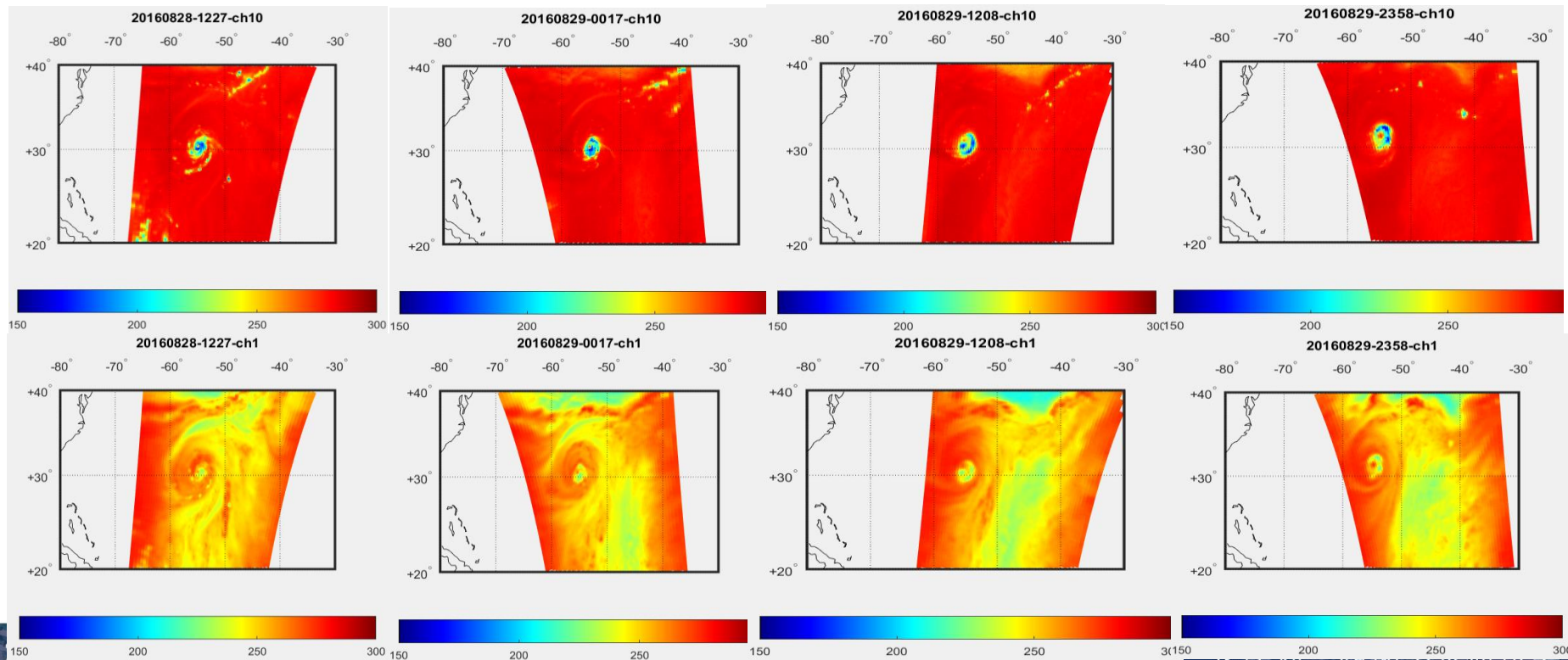


**grain**

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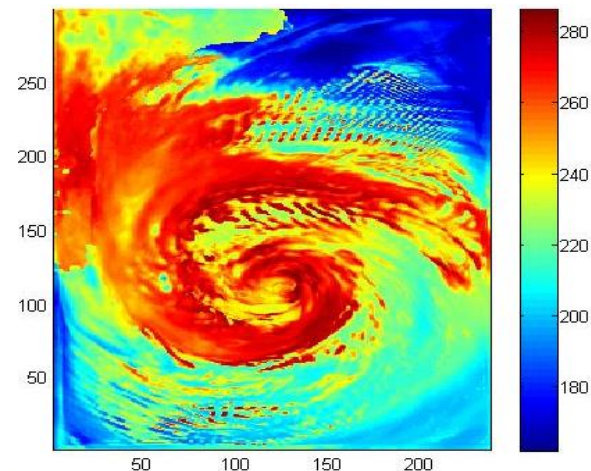
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# FY-3 mwhs-II observations

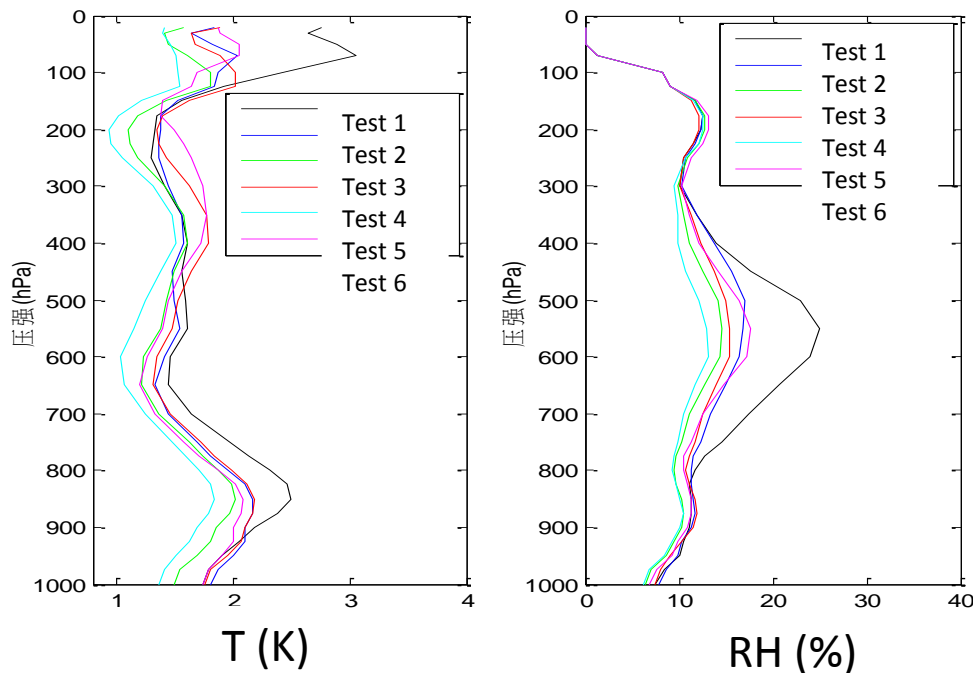


# Classification of hurricane area

1. Clear-air in hurricane-eye
2. **Convection in rain band (multi-state)**  
threshold: according to the precipitation
3. Stratiform (ice, cloud, rain)



# Results of retrievals



Hurricane area

# Precipitation retrievals between Jan,1 to Oct,31, 2016

Location	rain Rate(mm/h)	Land rms/K	sea rms/K	mean
Lat <30	0.1-1	1.02	1.84	1.43
	1-10	8.23	5.54	6.88
	10-30	20.31	21.23	21.77
30≤ Lat ≤60	0.1-1	1.11	1.35	1.23
	1-10	8.83	5.77	7.30
	10-30	20.81	22.26	21.72
Lat >60	0-1	0.72	0.54	0.63
	1-2	0.53	0.21	0.37
	2-5	1.31	1.03	1.17

Correlation coefficient:

Over ocean:  $R=0.6931$

Over land: 0.6245

Location	rain Rate(mm/h)	Land rms/K	sea rms/K
Typhoon/hurricane domain	0.1-1	/	0.84
	1-5	/	3.54
	5-10	/	6.78
	10-30	/	17.21
	30-50	/	21.23
	50-65	/	32.4



## Summary and further plan

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- Focus on calibration, validation and Quality control of observations
- Temperature and humidity retrievals based on observations and simulation.
- Study case on hurricane.

# Acknowledgement

Collaborators:

Ralf Bennartz, Frank Fell

From

- Earth and Environmental Sciences, Vanderbilt University, Nashville, US;
- Space Science and Engineering Center, University of Wisconsin – Madison, US;
- Informus GmbH, Berlin, Germany

# Thanks!

Any advice or comments?

Email: [hejieying@mirslab.cn](mailto:hejieying@mirslab.cn)