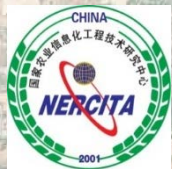


FIELD-BASED HIGH-THROUGHPUT PHENOTYPING (FBP) IN CROP BREEDING USING UAV PLATFORMS

Guijun Yang, Jiangang Liu, Chunjiang Zhao, Bo Xu



yanggj@nercita.org.cn; 86-10+51503647

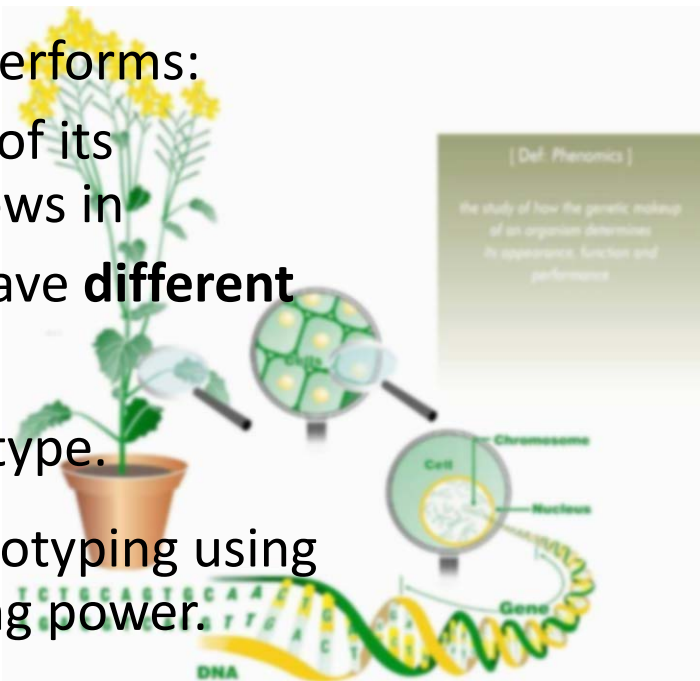
National Engineering Research Center for Information Technology in
Agriculture (NERCITA), Beijing, China

June 28, 2017

Kobenhavn, DANMARK

$$\text{Phenome} = \text{Genome} \times \text{Environment}$$

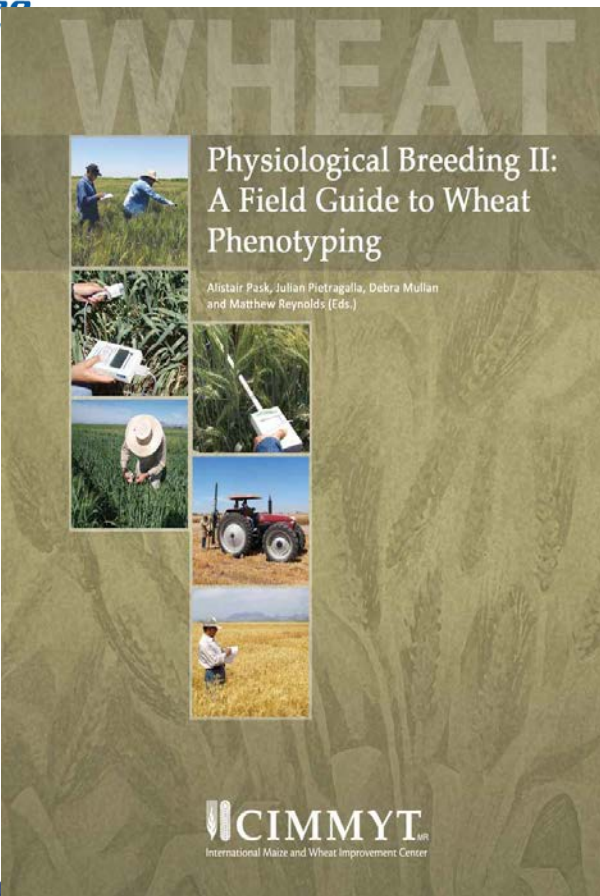
- A crop's **phenotype** is how it looks and performs:
 - a crop's phenotype is a combination of its genotype and the environment it grows in
 - crops with the **same** genotype can have **different** phenotypes.
- **Phenotyping** is analysing a crop's phenotype.
- **Phenomics** is a way of speeding up phenotyping using high-tech imaging systems and computing power.



Phenotype: bottleneck of molecular breeding

- **135 million** sequence data in traditional GenBank data store which contains **126.5 billion** base pairs (2011);
- BGI China's amount of sequence data is about **30PB** every year;
- **Speeding up phenotyping and linking phenotype with vast amount of genotype is in urgent need, especially in the field phenotype.**





2017 DRAGON 4 SYMPOSIUM

26-30 June 2017 | Copenhagen, Denmark

Measurement	Seedling development	Tillering	Stem elongation	Booting	Heading	Flowering	Early grain-filling	Late grain-filling	Ripening
Canopy temperature									
Stomatal conductance									
Leaf water potential									
Osmotic adjustment									
Leaf relative water content									
CID for potential TE (leaf tissue)									
CID for water uptake (grain)									
Spectral reflectance									
NDVI for growth analysis									
NDVI for pigments									
NDVI for senescence									
Chlorophyll content									
Crop ground cover									
Light Interception									
Green area index/Leaf area index									
Gas exchange and canopy fluorescence									
In-season biomass									
Water soluble carbohydrates									
Soil coring for root content									
Soil coring for moisture content									
Yield and yield components									
Crop morphological traits									

CID = carbon isotope discrimination; NDVI = Normalized difference vegetation index; TE = transpiration efficiency.

Key:

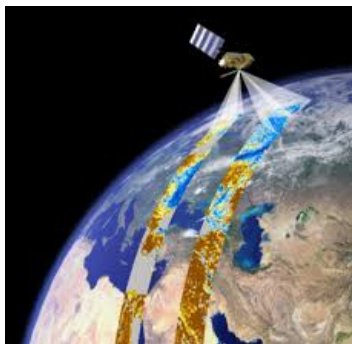
Most typical time to take measurements

Measurements taken related to objectives

Not recommended for measurements taken on the same day where phenology range >5 days, or during senescence

学术研讨会
，丹麦 哥本哈根

Remote Sensing Platforms for High Throughput Above Ground Phenotyping



“Traditional” Spacecraft

Constellations of Small Satellites



Proximal Platforms



Manned Aircraft and UAV



2017 DRAGON 4 SYMPOSIUM

26–30 June 2017 | Copenhagen, Denmark

四期学术研讨会
26-30日, 丹麦 哥本哈根

Justification:

- In-field monitoring is expensive and access is limited during most of the growing season.
- Space-based sensors have fixed orbits and many are impacted by cloud cover
- Manned aircraft are costly and limited in availability.
- UAV can provide low cost information “on demand” for targeted problems.

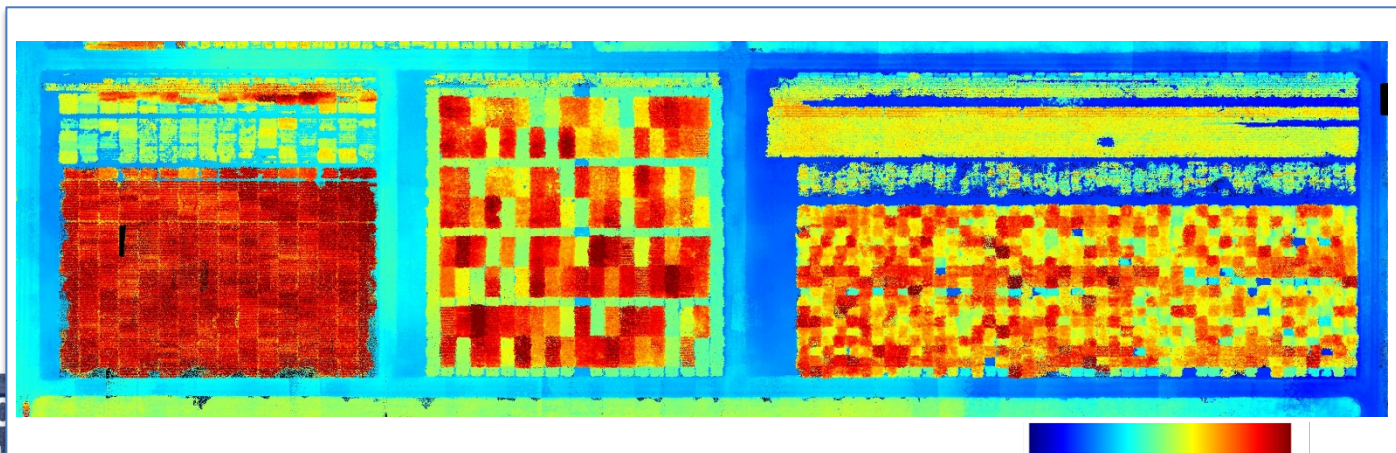
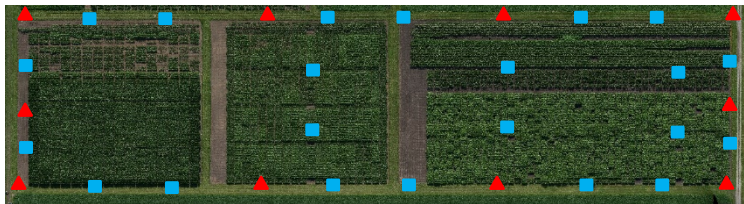
Government agencies, universities, commercial companies are all players



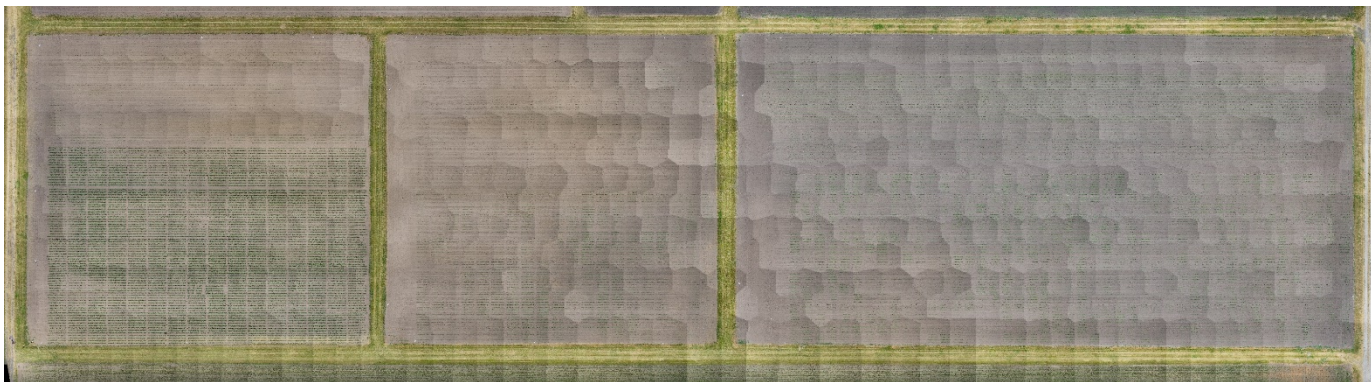
Remote Sensing for Phenotyping vs Crop monitoring: How is it different?

Improved positioning required for multi-temporal acquisitions

- Surveyed targets provide improved positioning for frame cameras whose positioning is determined by autopilot with consumer grade GPS/IMU



RGB-based Orthophoto June 13, 2016



RGB-based Orthophoto June 21, 2016



RGB-based Orthophoto June 30, 2016



RGB-based Orthophoto July 15, 2016



RGB-based Orthophoto July 19, 2016



RGB-based Orthophoto July 27, 2016



RGB-based Orthophoto August 9, 2016

Pre-lodging



RGB-based Orthophoto aug 17, 2016

Post-lodging



June 15

June 26

1 2

4 3

2017 DRAG

26-30 June 2017

July 15

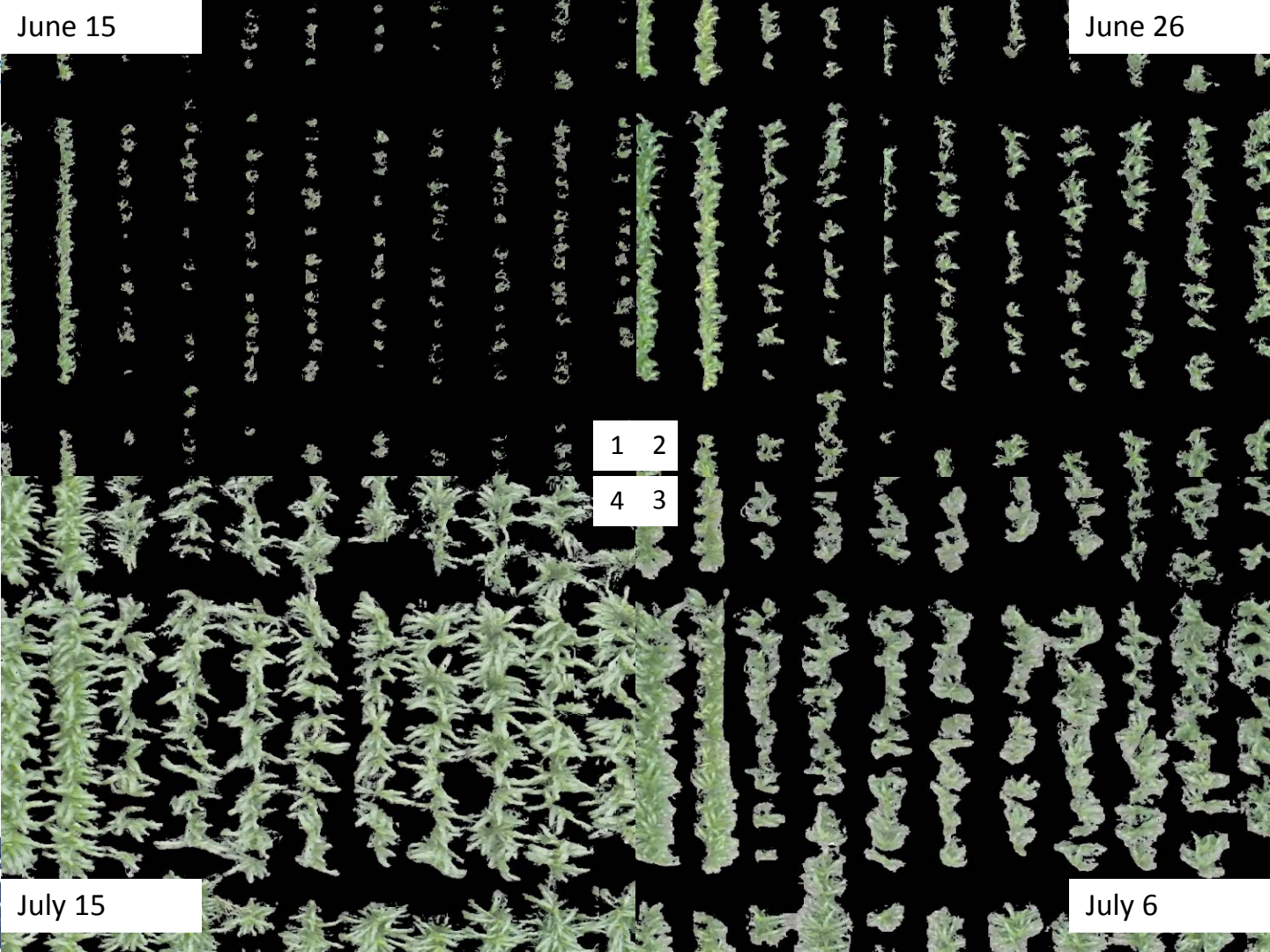
July 6

明学术研讨会

日, 丹麦 哥本哈根

June 15

June 26



1 2
4 3

2017 DRAG

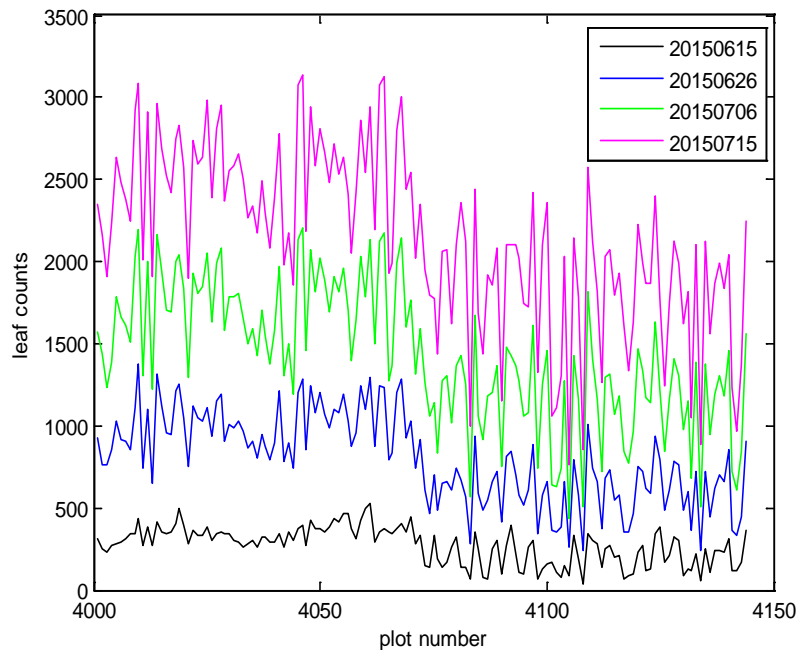
26-30 June 2017

July 15

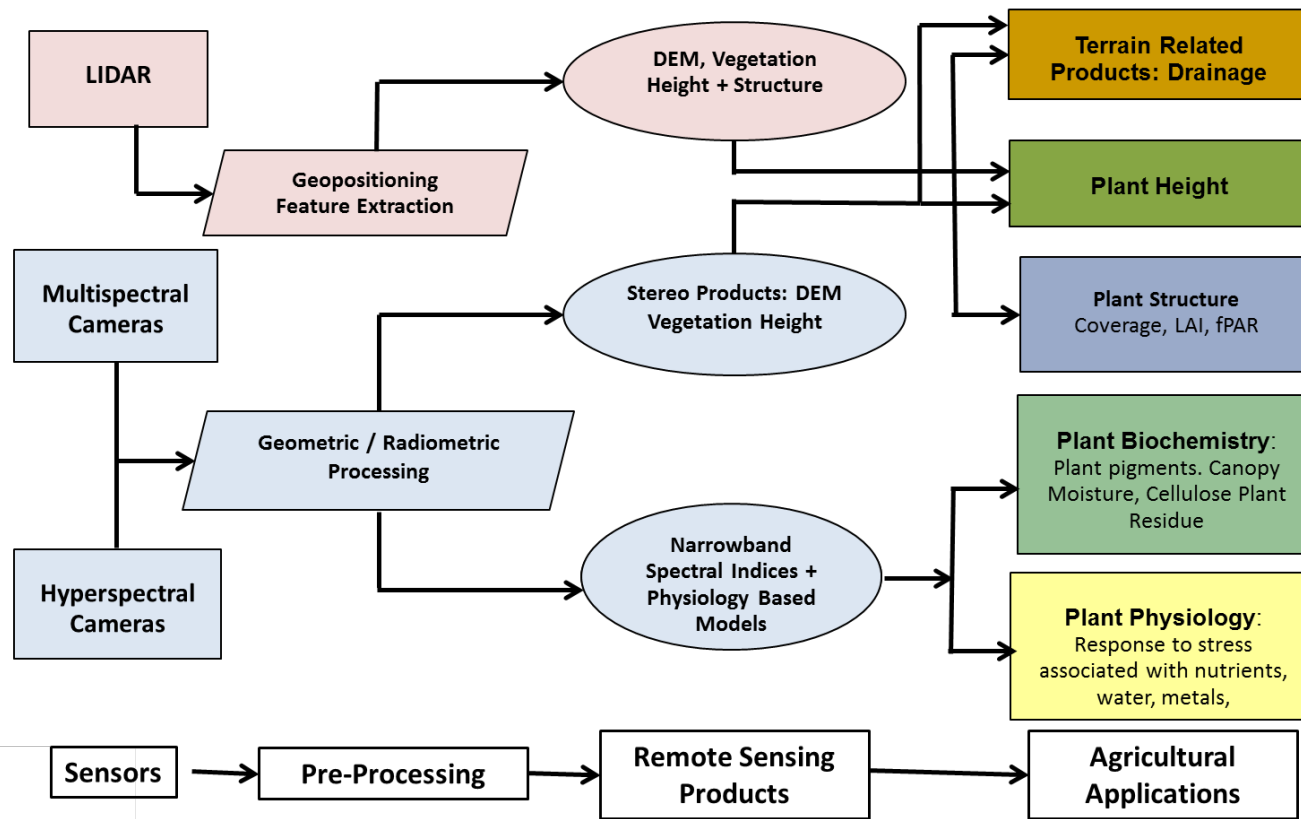
July 6

月学术研讨会

日, 丹麦 哥本哈根



Average	20150615	20150626	20150706	20150715
Accumulated Leaf counts	271.9	802.8	1431.7	2146



■ HD camera: Can be used to map orthophoto in large scale

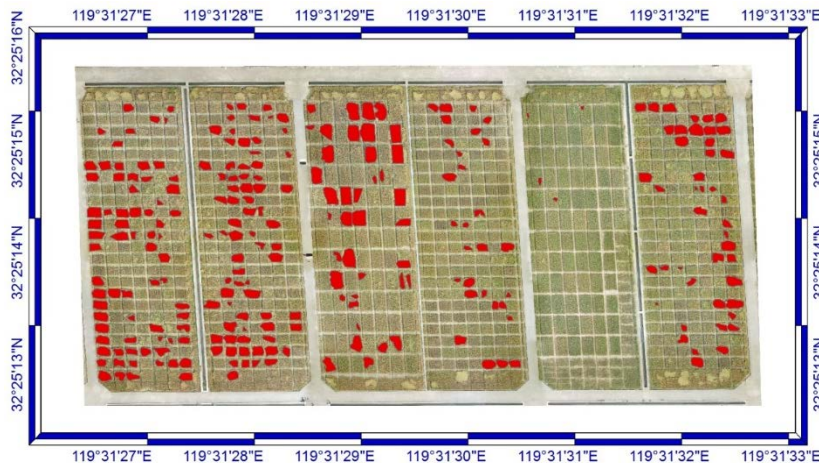


Height: 50m

Resolution: 1cm

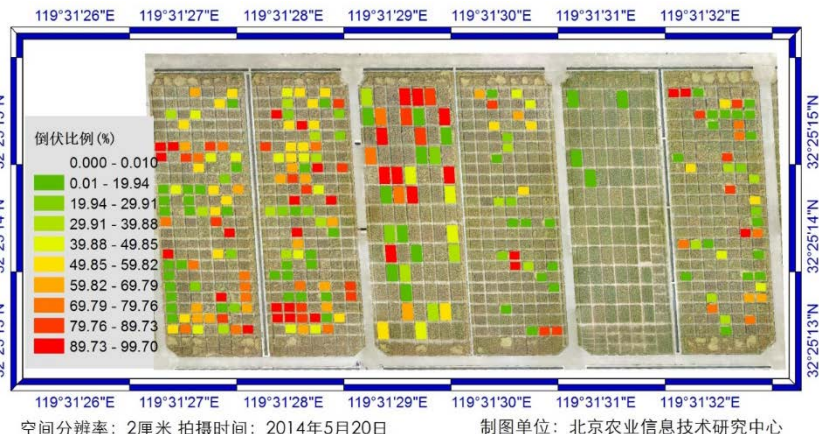


Pixels: 4000*5000, Zoom: 35mm, Weight: <500g, GPS supported



空间分辨率: 2厘米 拍摄时间: 2014年5月20日

制图单位: 北京农业信息技术研究中心



空间分辨率: 2厘米 拍摄时间: 2014年5月20日

制图单位: 北京农业信息技术研究中心

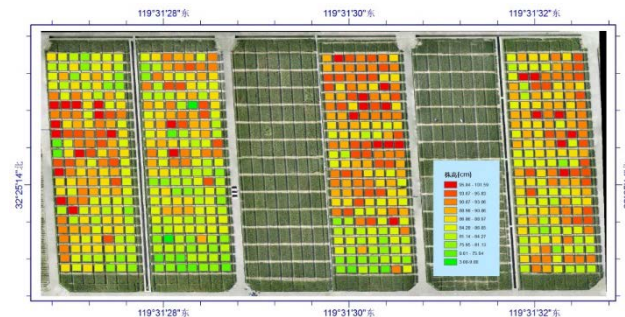
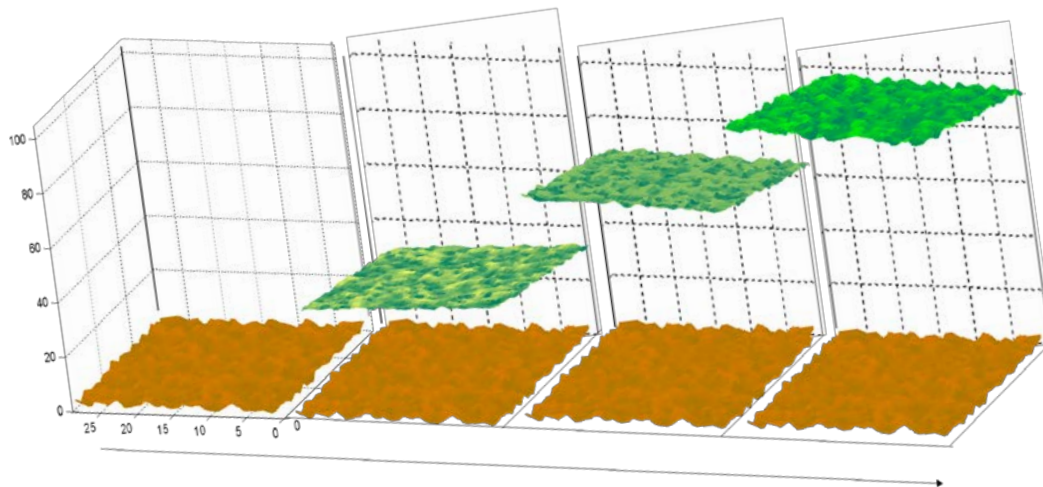
➤ Lodging area and distribution

The lodging region segmentation was identified by image recognition method according to the HD Orthophoto.

➤ Estimation of lodging proportion

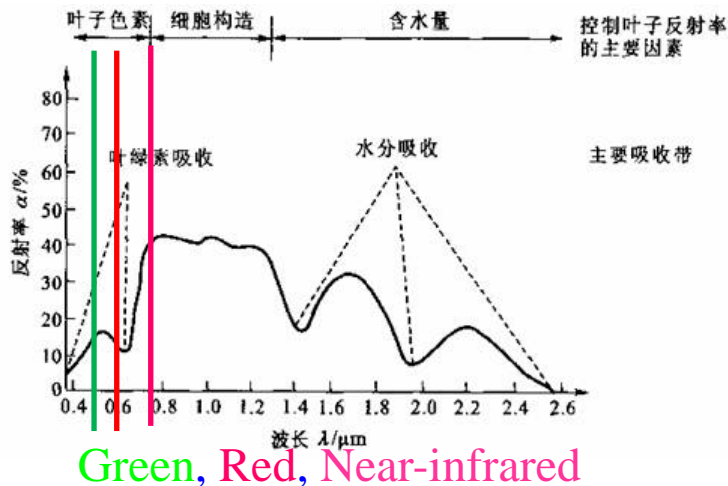
To estimate the lodging proportion and apply classification on breeding plots.

Combining high-definition digital images and POS data, DSM can be generated based on the point cloud data. The wheat height can be obtained by subtracting the DSM from ground elevation.



Wheat plant height

- **Multispectral camera:** For extraction of NDVI, chlorophyll and biomass...

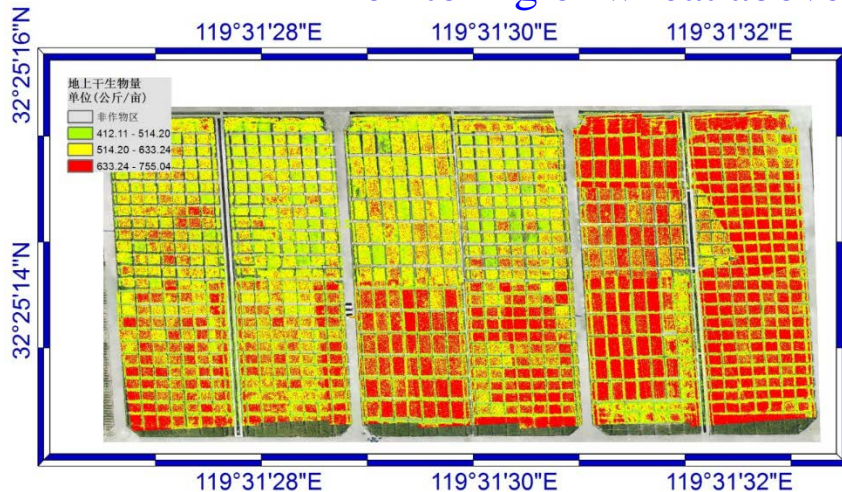


- Pixels: 2048x1536
- Focal length: 8.5mm
- Bands: 4
- Acquisition speed: 2-5 s per image

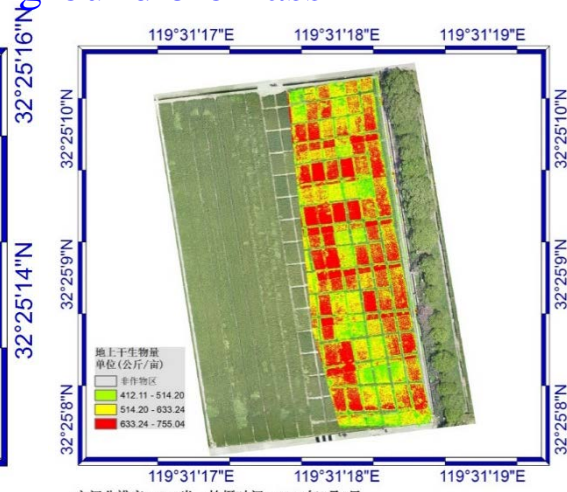
The wavelength range is 520nm-920nm, which is sensitive to crop chlorophyll, biomass and LAI. The sensor is mainly used for detecting the status of vegetation growth and coverage.

The biomass monitoring model is established by data from **multiple growing stages**. Here, the **crop height** as a key factor combination with hyperspectral imaging data to build model.

Monitoring of wheat above-ground biomass

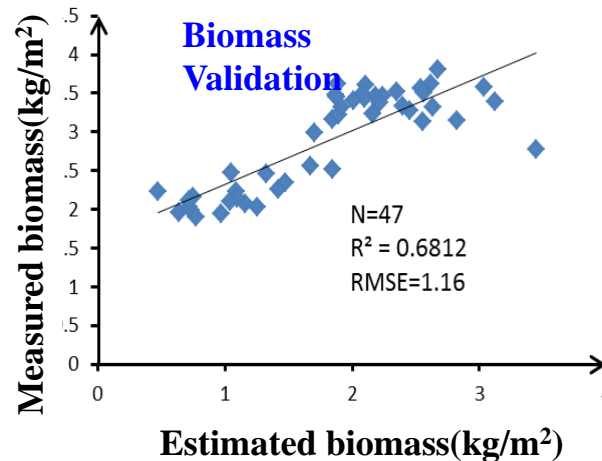
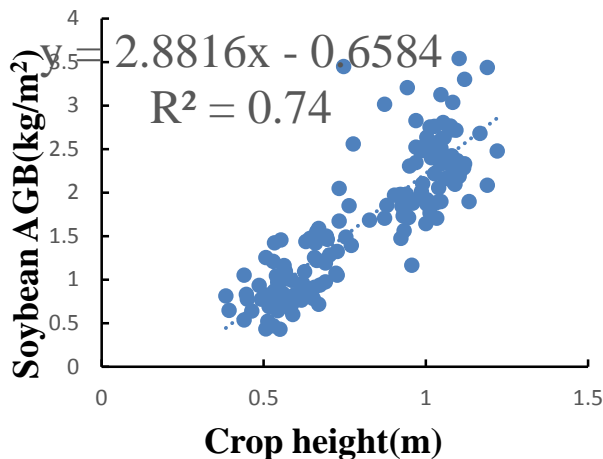
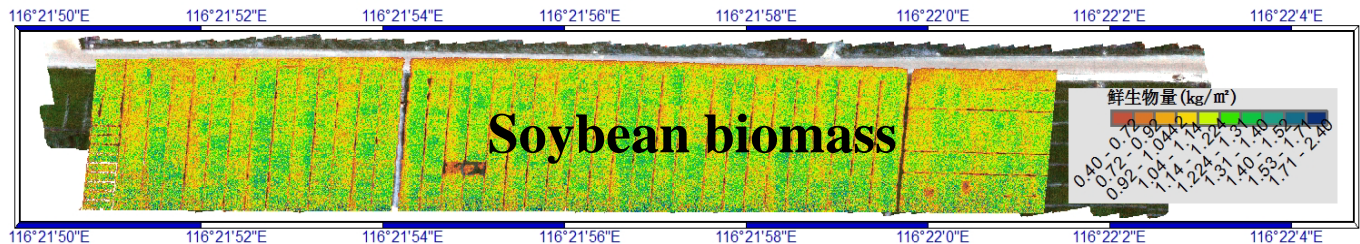


空间分辨率: 0.3米, 拍摄时间: 2014年5月8日 制图单位: 北京农业信息技术研究中心

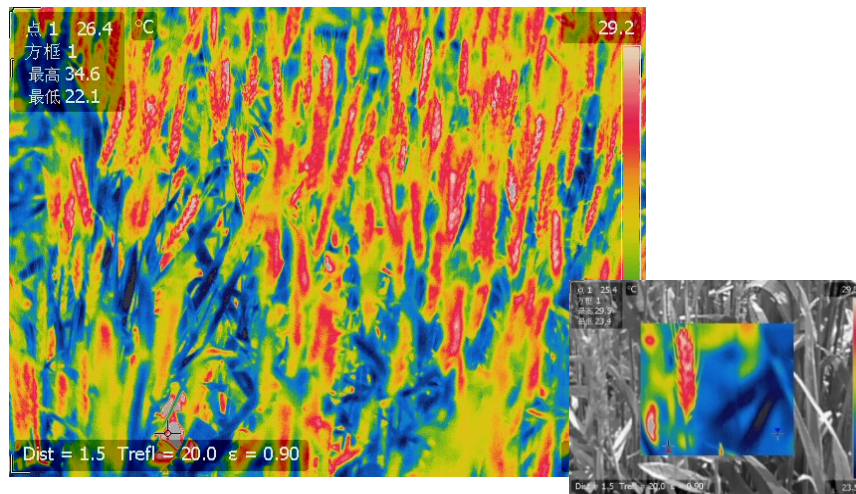


空间分辨率: 0.3米, 拍摄时间: 2014年5月8日

制图单位: 北京农业信息技术研究中心



■ Thermal Imager: Used for crop canopy temperature acquisition



Accuracy: $\pm 2\%$

Pixels: 382×288

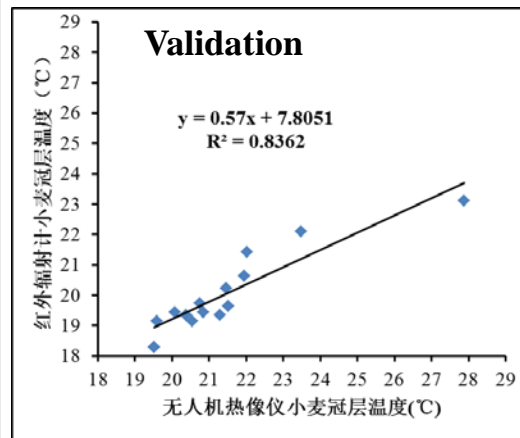
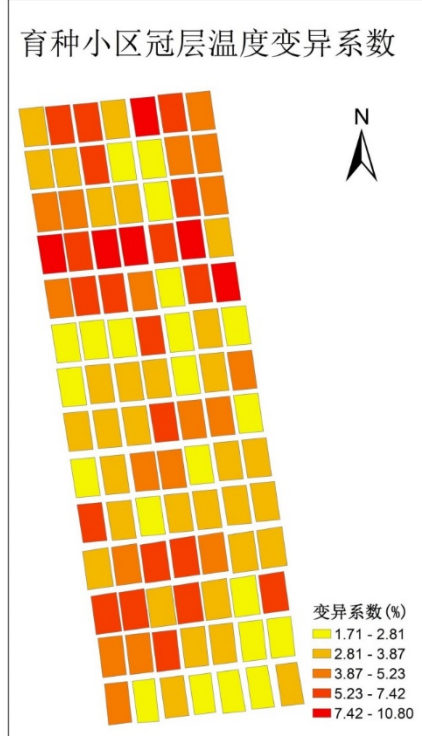
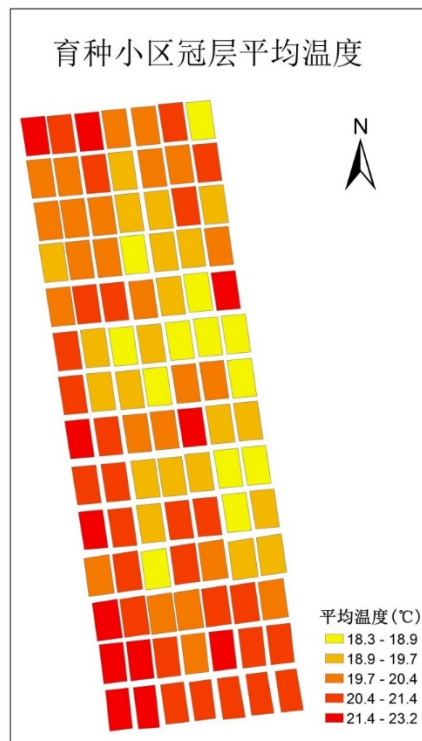
Angle: $38^\circ \times 29^\circ$

Frequency: 0~80Hz

Measuring range: $-20 \sim 100^\circ\text{C}$

Wavelength range: $7.5 \sim 13\mu\text{m}$

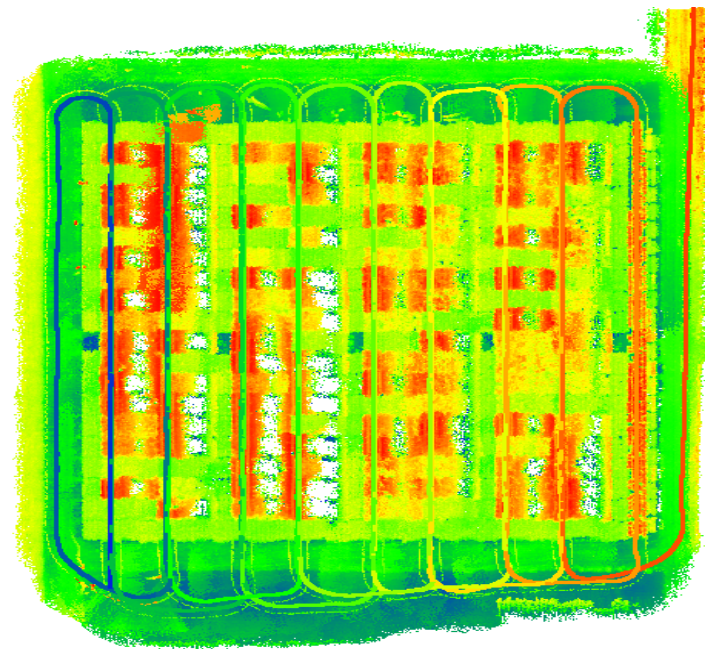
Crop canopy temperature can be obtained dynamically in video format. In which, each frame can be extracted both in image and text format.

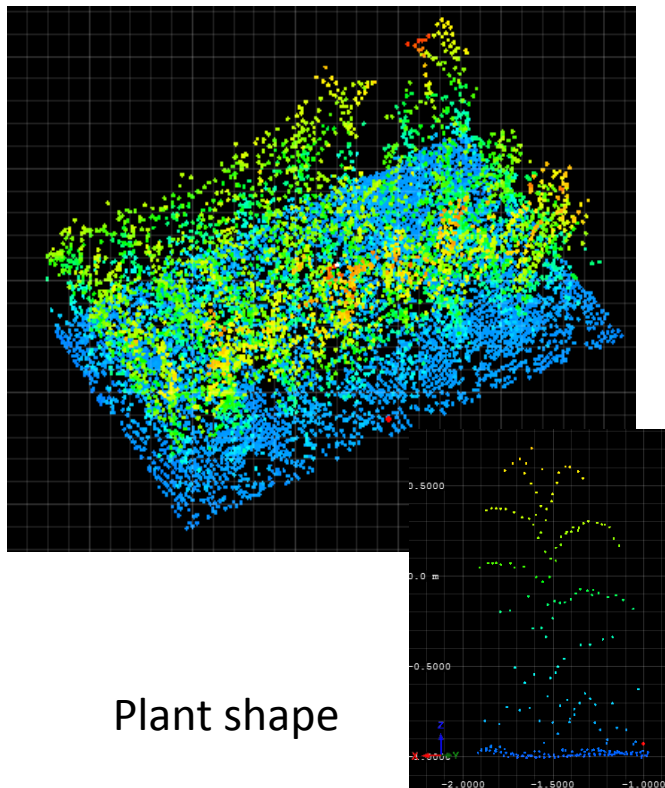


The results indicated that UAV thermal imager can be used to monitor the winter wheat canopy temperature with high accuracy ($R^2=0.84$, $RMSE=1.77$, $n=14$).

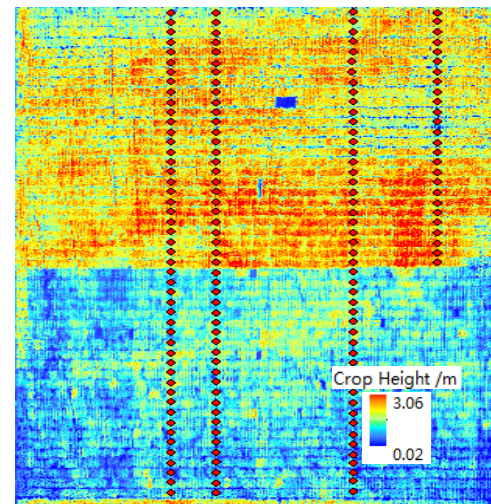
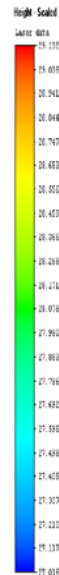
Average temperature map Temperature variation

LiDAR for Phenotyping: Plant Height and “structure”

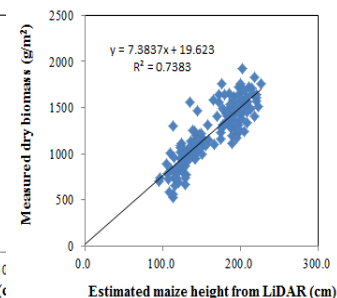
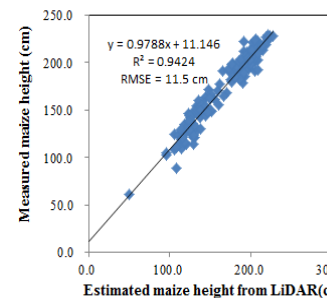




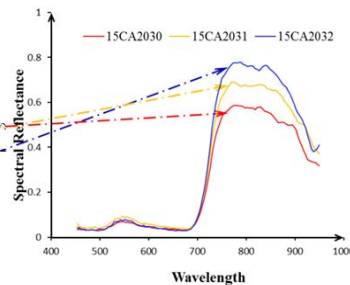
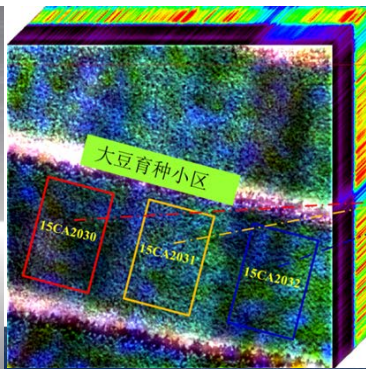
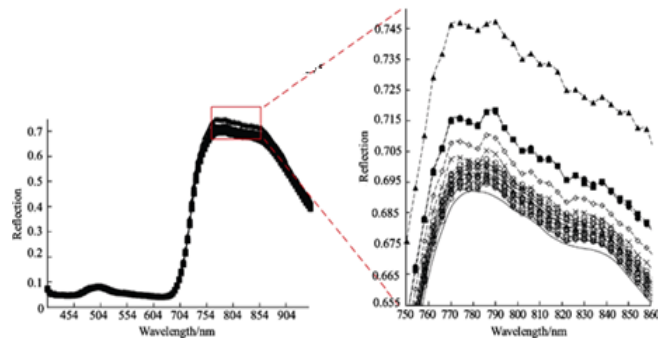
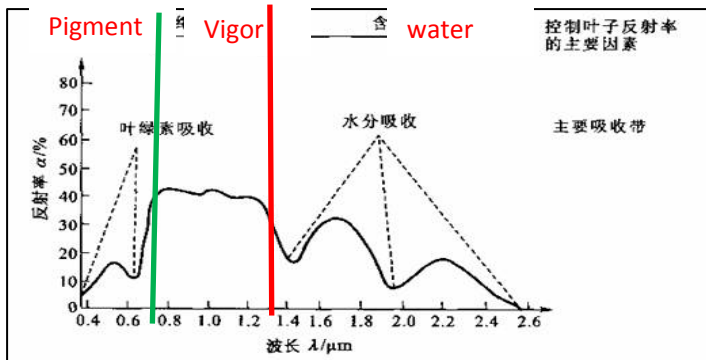
Plant shape

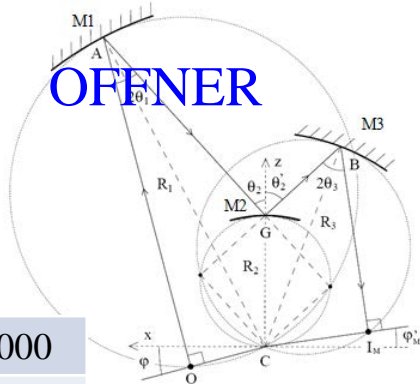
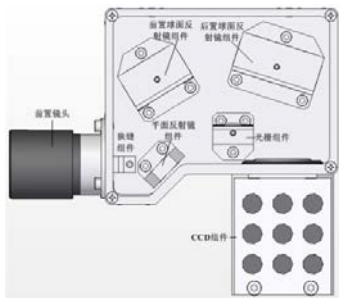


Maize height (m)



■ **Hyper-spectral Imager:** Can accurately reflect the difference of spectral characteristics between crop breeding plots.





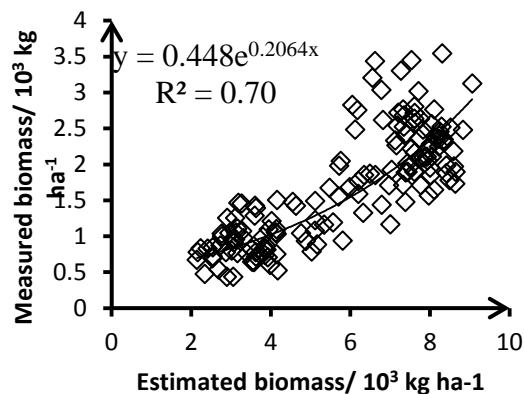
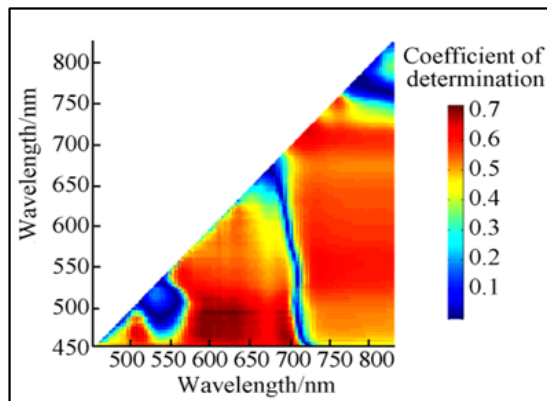
Wavelength range (nm)	400~1000
Spectral resolution (nm)	4@500 nm
Scanning speed (lines, images/s)	15-60
Push broom linewidth (m, 10m away)	8
Pixel Resolution (m, 10m away)	0.004
focal length (mm)	25
FOV (°)	20
Weight (g)	915

Spectral imaging :OFFNER
reflective imaging
spectrometer

High spectral resolution,
high SNR, Small size, light
weight suitable for UAV
platform

Table. Order of grey correlation degree between vegetation index and biomass

assessment index	grey correlation degree ($\varepsilon=0.5$)	order	assessment index	grey correlation degree ($\varepsilon=0.5$)	order
RVI	0.82	1	OSAVI	0.49	6
R_1	0.75	2	R_2	0.48	7
VOG1	0.64	3	DVI	0.484	8
NDVI	0.51	4	PRI	0.456	9
$NDVI_{705}$	0.50	5			



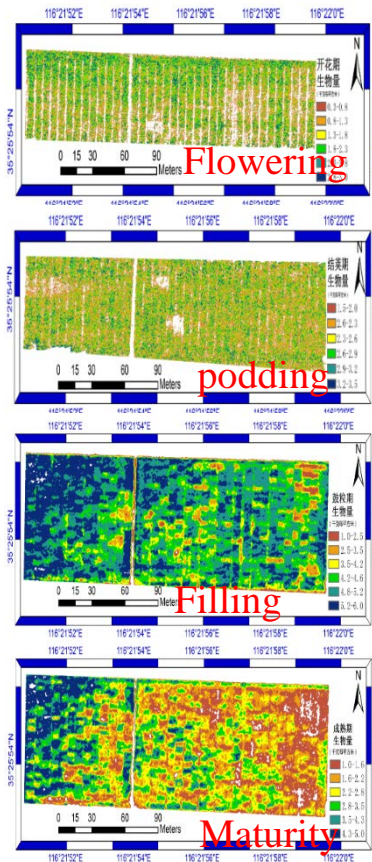
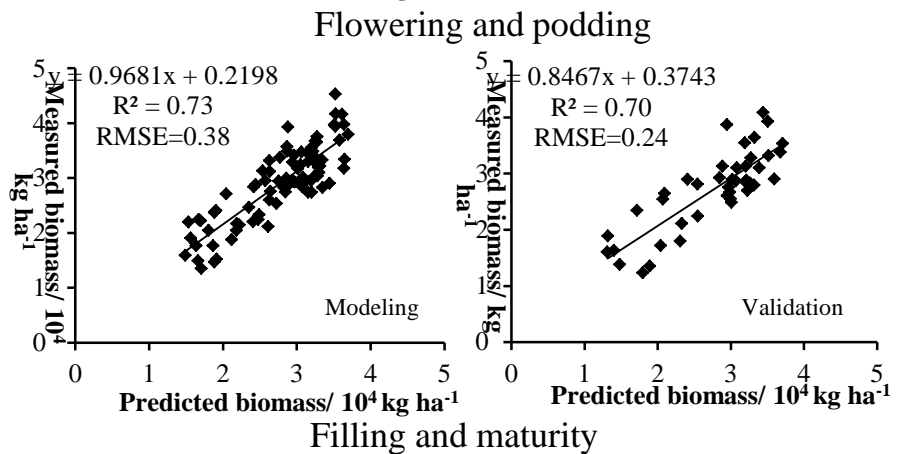
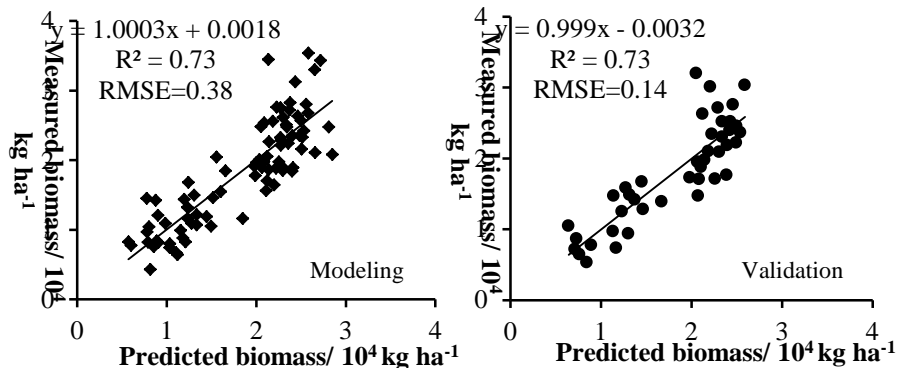


Fig. 1 Yield prediction based on NDVI of R5

Function type	Sensitive band combination 1		Sensitive band combination 2	
	(nm)	(nm)	(nm)	(nm)
	695-1350	503-713	1569-1793	577-696
Linear	0.000-0.692		0.455-0.604	
Power	0.520-0.709		0.471-0.625	
Exponential	0.515-0.711		0.466-0.627	

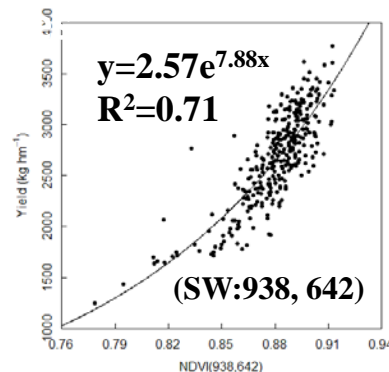


Fig. 2 Yield prediction based on NDVI of multi-growth stages

Growth stage	Regression equation	Model test	Model parametric test				R^2	RMSE
			x_1	x_2	x_3	Intercept		
R2,R5	$y = e^{0.39+1.39x_1+7.17x_3}$	$P<0.01$	0.39**		1.39**	7.17**	0.728	249.47
R4,R5	$y = e^{-2.01+4.87x_2+6.20x_3}$	$P<0.01$		-2.01**	4.87**	6.20**	0.751	237.32
R2,R4,R5	$y = e^{-2.16+1.02x_1+4.44x_2+5.82x_3}$	$P<0.01$	1.02**	4.44**	5.82**	-2.16**	0.760	232.69

Note: R2: Flowering; R4: Podding; R5: Pod filling $y=e^{-2.16+1.02x_1+4.44x_2+5.82x_3}$

UAV-based crop phenotyping in breeding

What can we measure now?

- Canopy height
- Leaf color
- Chlorophyll
- Lodging area
- N content
- Canopy temperature
- powdery mildew
- Biomass
- LAI
- Yield

What are we working on?

- Increasing the precision and replication of retrieving models
- Fusion of spectrum and thermal data to predict yield
- Determining the strategies for phenotyping different crops
- Ready for providing service to breeders for field phenotyping

Published Journal Papers

No	Title	Journal	
1	Retrieving Soybean Leaf Area Index from UnmannedAerial Vehicle Hyperspectral Remote Sensing:Analysis of RF, ANN, and SVM Regression Models	Remote Sensing,2017	SCI
2	Geometric Correction Method of Rotary Scanning Hyperspectral Image in Agriculture Application	Remote Sensing,2017	SCI
3	Comparison of three regression methods for the winter wheat biomass estimation using hyperspectral data	Remote Sensing,2017	SCI
4	Unmanned aerial vehicle remote sensing for field-based crop phenotyping: Current status and perspectives	Frontiers in Plant Science ,2017	SCI
5	The DOM Generation and Precise Radiometric Calibration of A UAV-mounted Miniature Snapshot Hyperspectral Imager	Remote Sensing,2017	SCI
6	农用无人机多传感器遥感辅助小麦育种信息获取	农业工程学报,2014	EI
7	无人机多光谱影像辐射一致性自动校正	农业工程学报,2013	EI
8	无人机遥感解析田间作物表型信息研究进展	农业工程学报,2016	EI
9	基于无人机高光谱遥感的冬小麦叶面积指数反演	农业工程学报,2017	EI
10	基于无人机组载高光谱空间尺度优化的大豆育种产量估算	农业工程学报,2016	EI
11	基于无人机数码影像的冬小麦叶面积指数探测研究	中国生态农业学报,2016	核心
12	基于无 人机搭载数码相机的小麦盲种表型信息解析	中国种业,2016	核心
13	基于成像高光谱仪的大豆叶面积指数反演研究	大豆科学,2016	核心
14	基于无人机组载LIDAR数据的玉米涝灾灾情评估	中国农业科学,2016	核心

Conclusion and Summary

1. UAV remote sensing technology is a good supplement for airborne, satellite remote sensing and ground observations.
2. UAV remote sensing has a huge potential values for large scale crop breeding to improve breeding efficiency.
3. It is also important that we should speed up data analysis and keep high estimation accuracy. Developing real time acquirement and processing system is needed in the future.
4. Determining the optimal methods, parameters and growth stages is very important for the crop phenotyping.

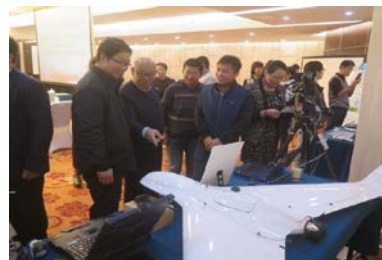
Acknowledgement



Junyi Gai

Xiaoyan Zhang

Jiqui Cao



Shunhe Cheng

Dongmei Zhu



Ruyang Zhang



Haiyang Yu

Bo Xu

Haikuan Feng

Xiaoqing Zhao



Thanks for your attention!

Email: yanggj@nercita.org.cn

[Tel: +86-10-51503647](tel:+86-10-51503647)

