

# Sea Ice Classification Using Satellite SAR: The lessons we learned

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## Focus is on:

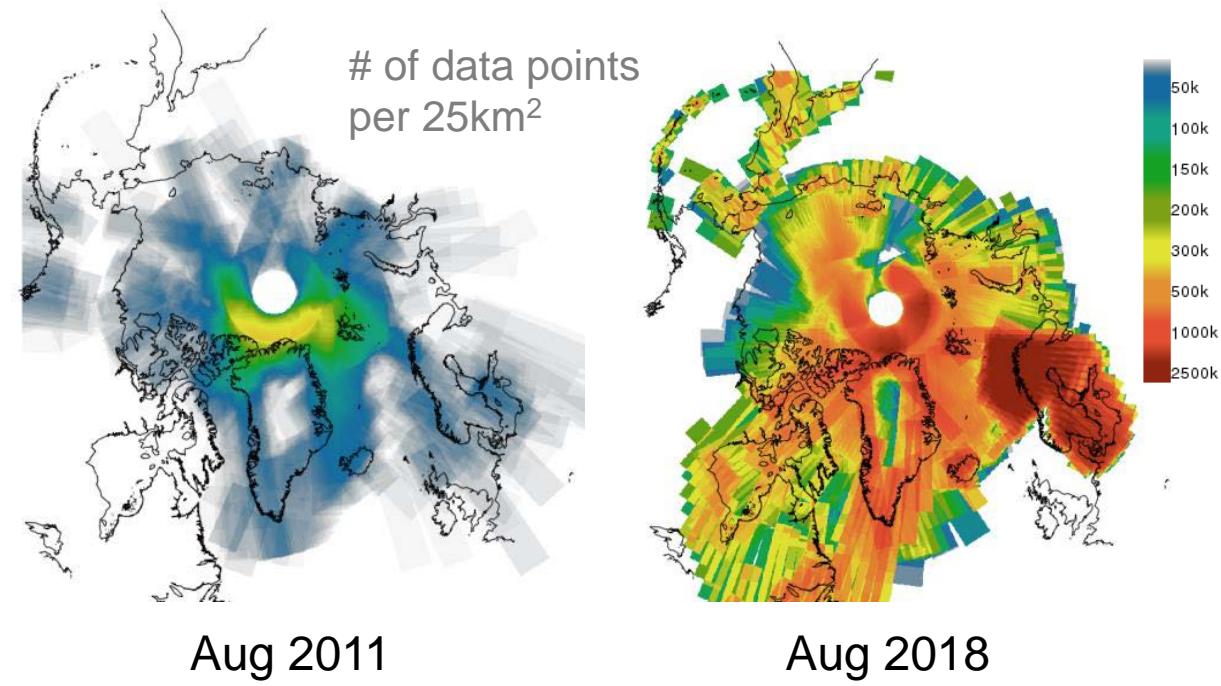
- Automated sea ice type mapping (ML, DL, ...)
- Feature extraction

## Automated sea ice type mapping

- to handle many data within short time
- to optimize processing schemes
- to reduce time-consuming human interference

# An intelligent system for SAR sea ice image classification: a preliminary study (Xi)

- We have SAR backscattering coefficients, texture and polarimetric parameters at different radar frequencies and polarizations
- We want to separate different ice types and features for operational ice charting and science studies
- Aim: create automated sea ice processing and classification systems



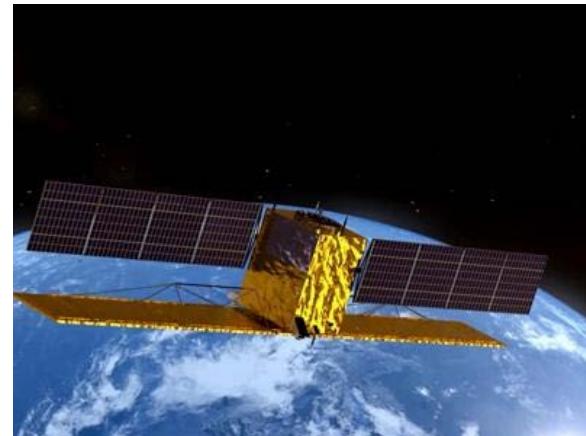
Andreas Cziferszky, 2018

## Software development environment

anaconda/python

## SAR data and process

- **Sentinel-1 A/B GRD** data is auto-downloaded and pre-processed using Python modules 'sentinelhub' and 'Nansat' (@github)
- **GF-3 data** is access via ftp which is provided from National Satellite Ocean Application Service; the pre-processed is done by a self-code.



## Training data: ice chart

- Arctic: **CIS Arctic Sea Ice Charts** (SIGRID-3 Format, weekly)
- The Bohai sea: **North China Sea Marine Forecasting Center** (MODIS and GOCI-based)



National Snow & Ice Data Center



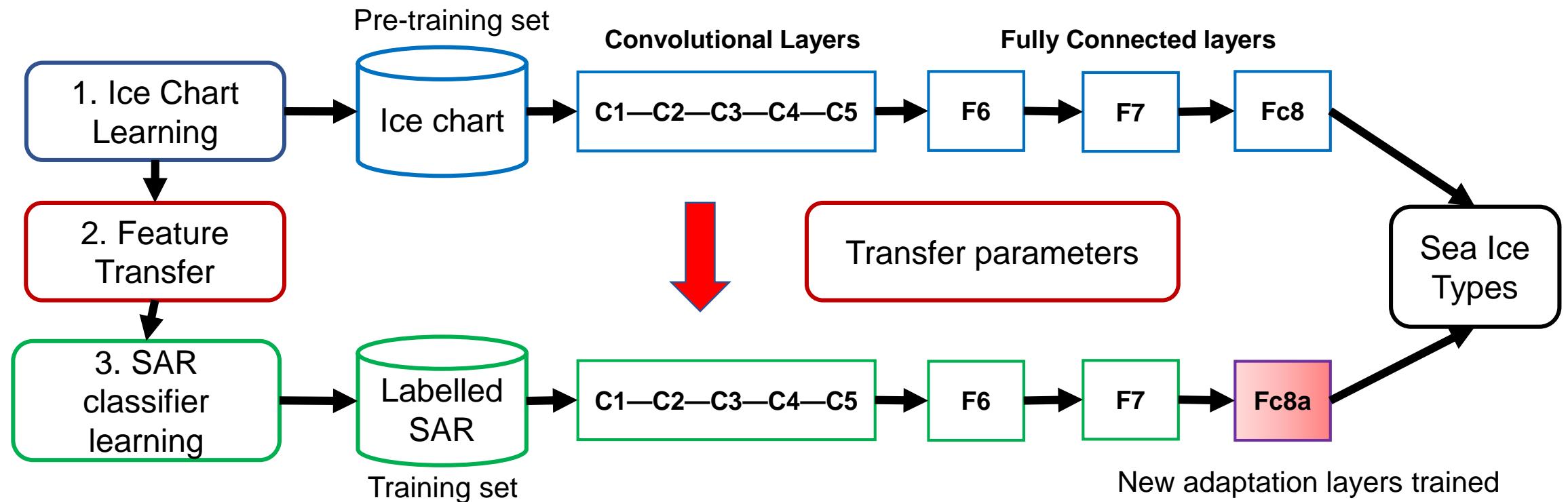
## Training data set

- Pre-training sets: only ice chart
- Training sets: SAR image which is labelled based on ice chart.
- Only ice concentration > 70% in winter and early spring is considered to use as pre - or training data set.

## Architecture of the system

### Transfer Learning + CNN

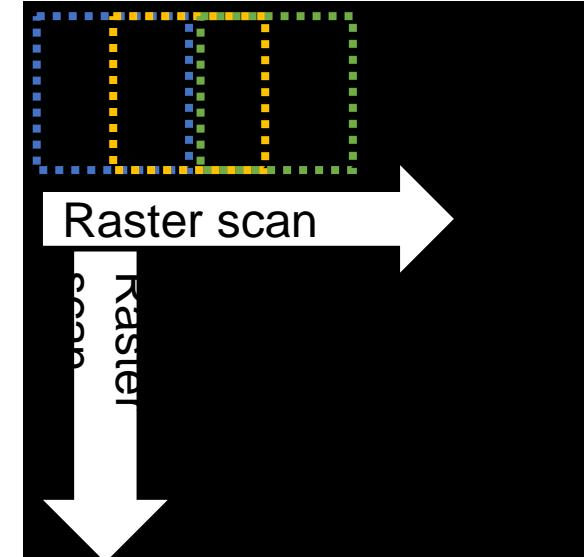
- Transfer learning: The system learns about sea ice feature characteristics from ice charts.
- CNN: inherits the knowledge from transfer learning and knowledge from SAR training set.



## The input of Transfer Learning

Characteristic extracted from ice chart

Area of the shapefile  
Perimeter of the shapefile  
Shape index of the shapefile  
Contiguity index of the shapefile  
Distance to the nearest neighboring type



## The input of CNN

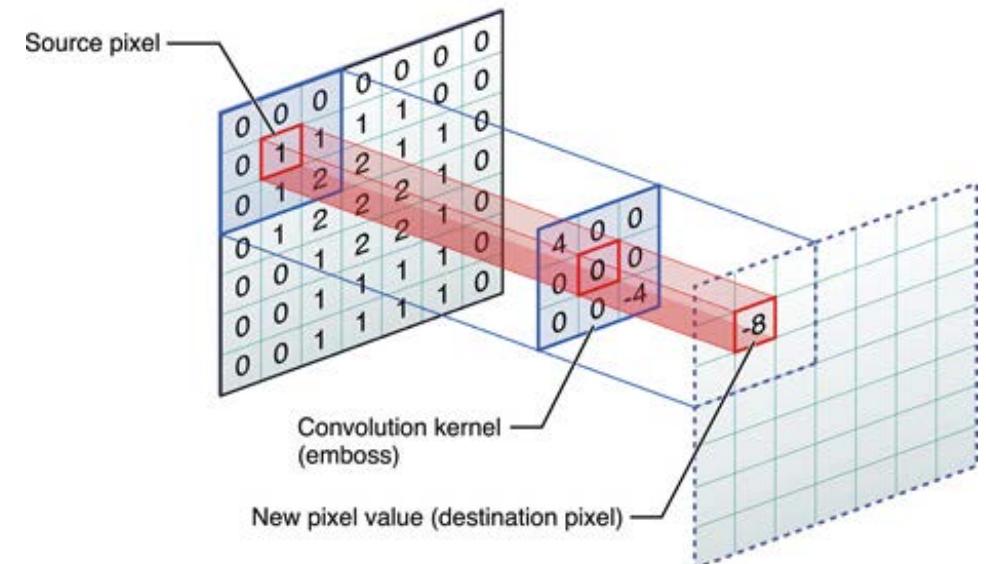
The input of the CNN mode used requires 3 dimensional data

HH, HV and incidence angle.

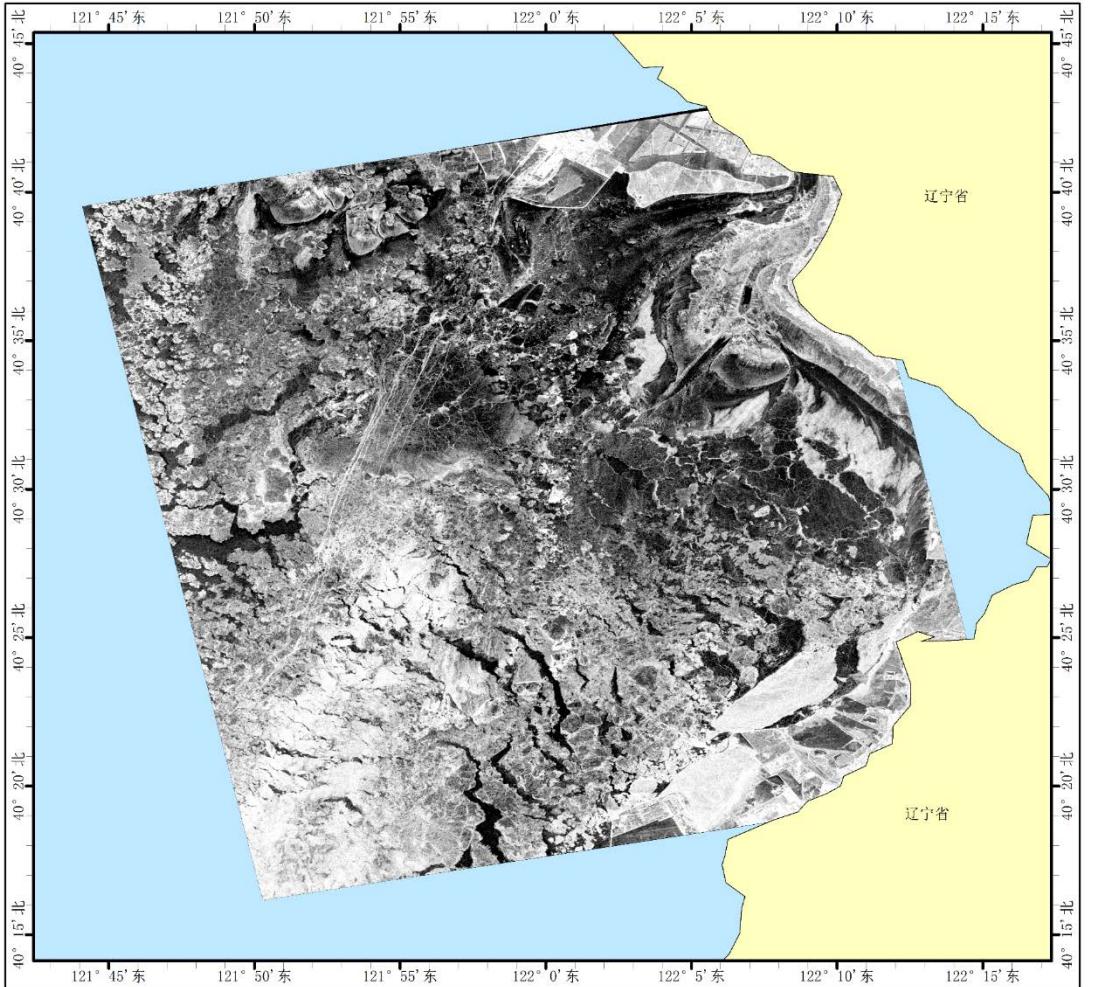
The size of each image patch is 45 pixels \* 45 pixels

## The work in process

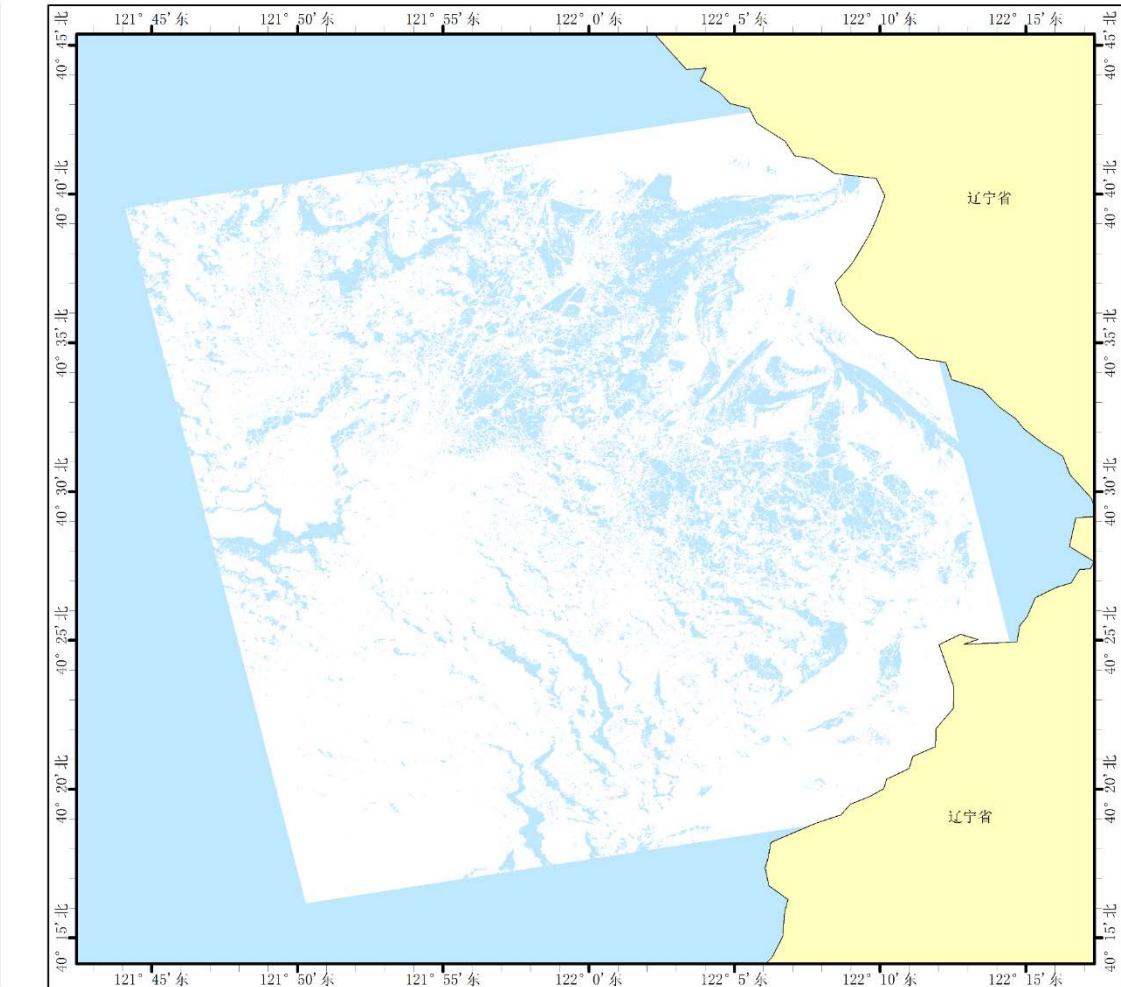
1. Optimize network parameters and network structure
2. Detailed assessment of classification performance
3. Analysis of results with or without pre-training
4. Parallel processing accelerates compute speed



# Preliminary classification results from Bohai Sea



2017.1.22, GF-3

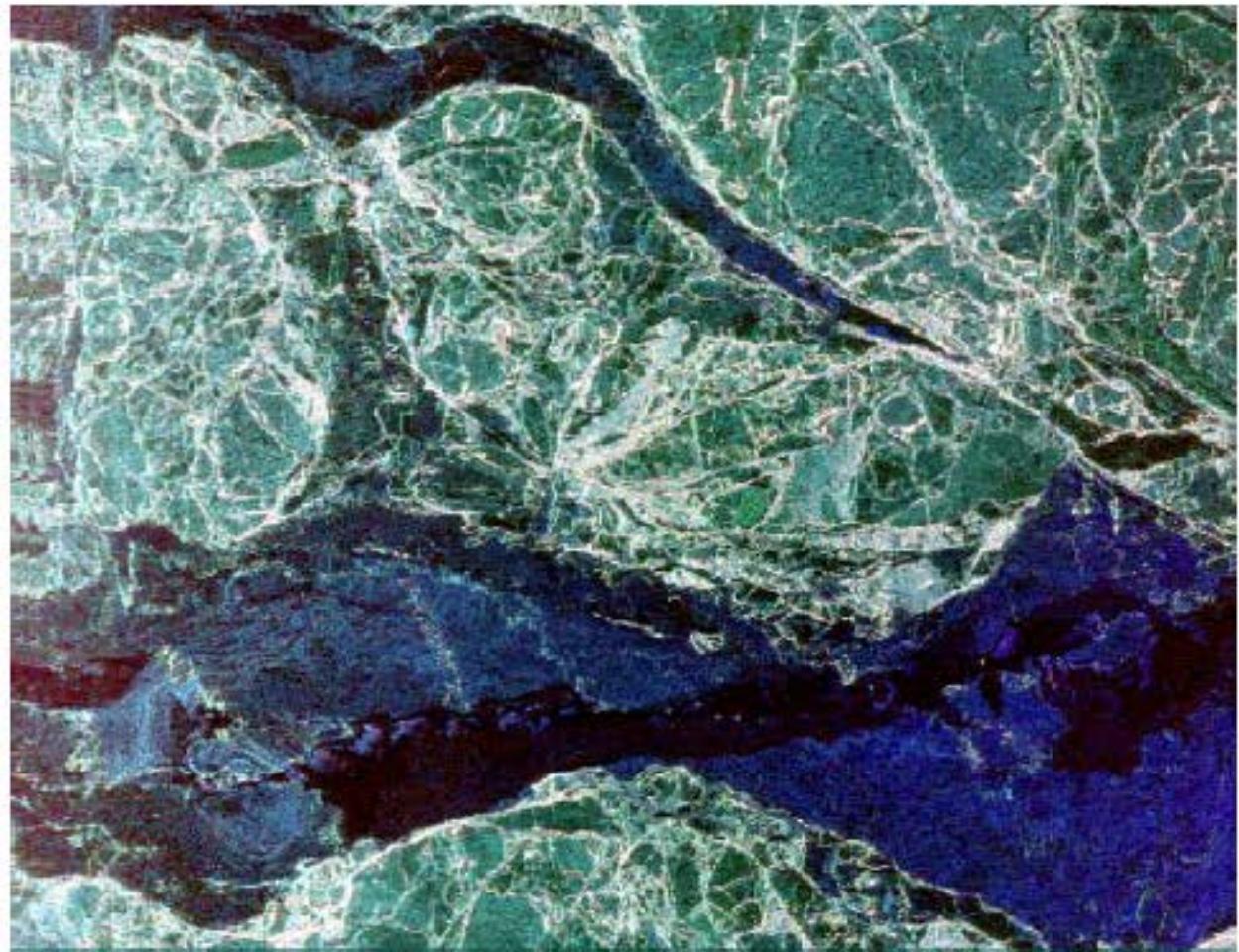


Sea ice detection

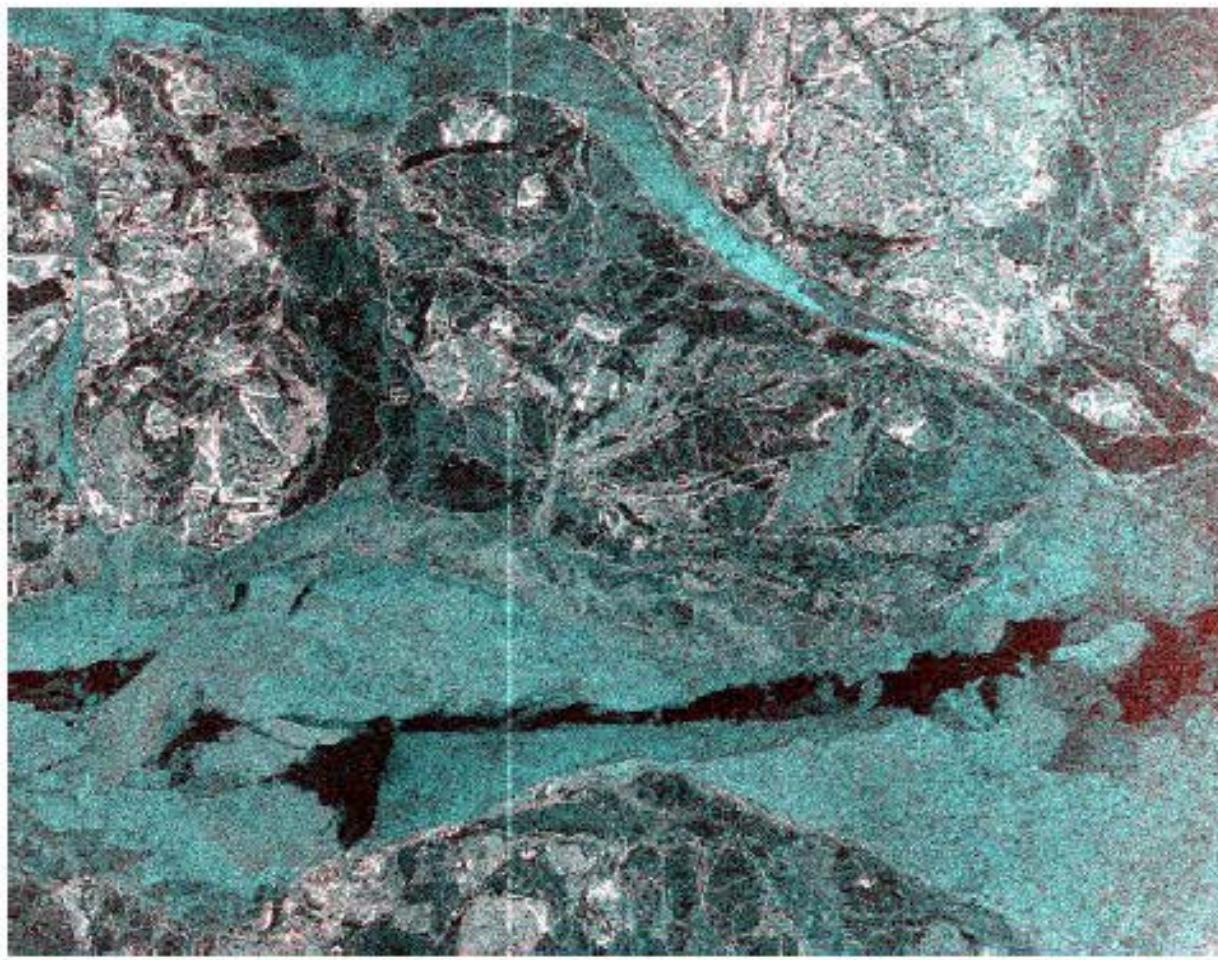


## But: there are many fish(es) in the sea:

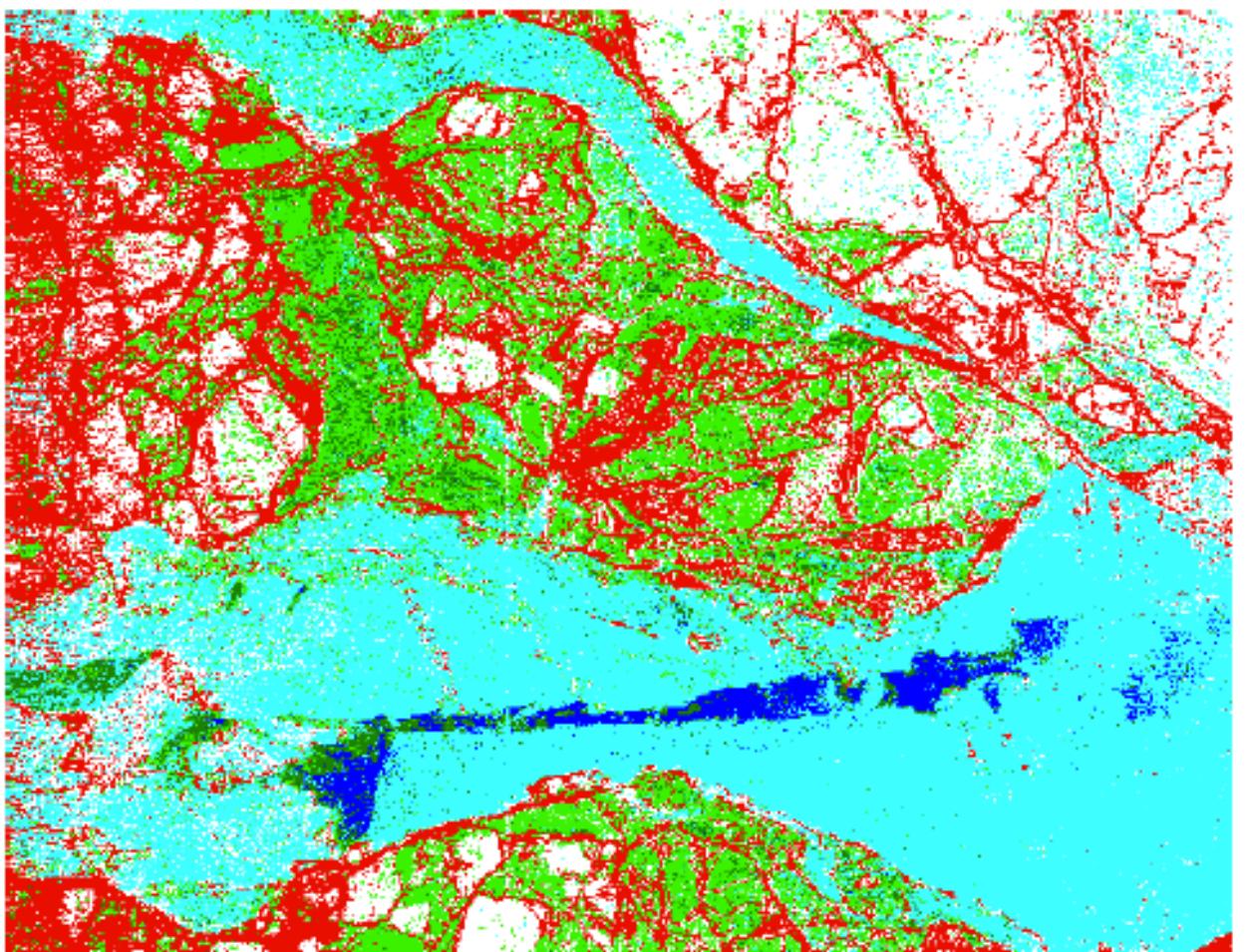
- Which segmentation / classification method is optimal?  
(reliability/accuracy, robustness, computation time)
- How much input information (i.e. parameters derived  
from SAR measurements) are needed?



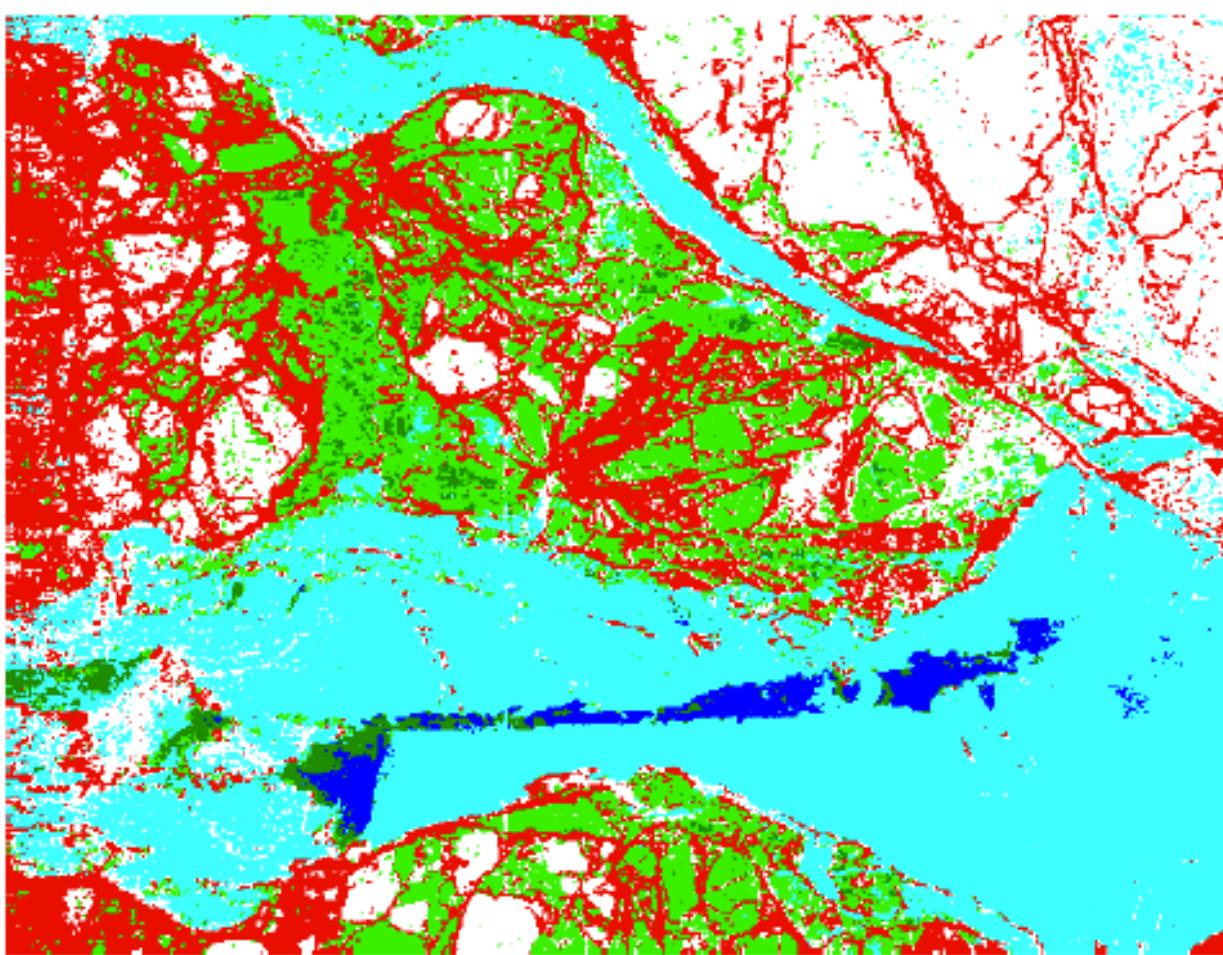
*L-band RGB: Cross-HH-VV*



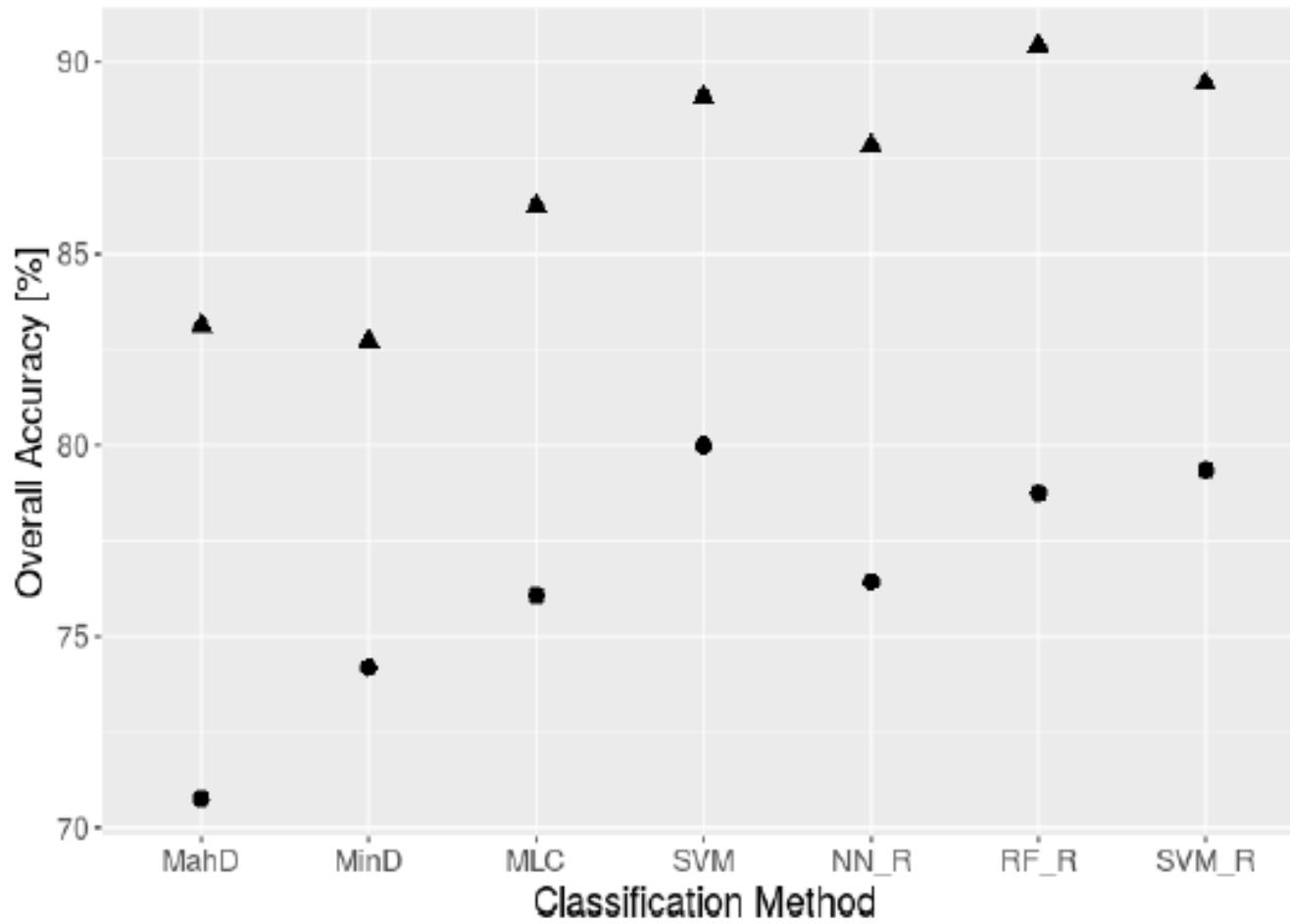
*C-band RGB: Cross-VV-VV*



*Support Vector Machine*

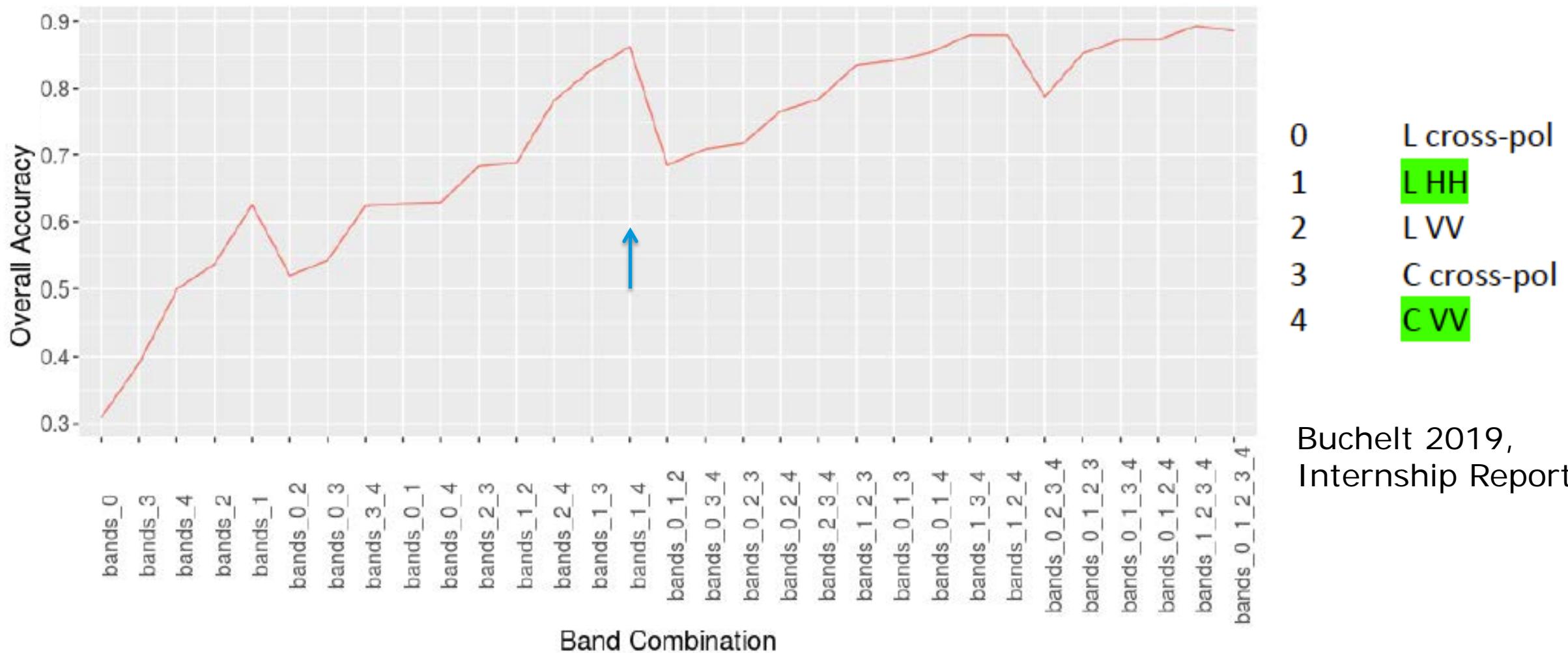


*Support Vector Machine with Majority Filter 5x5*



Buchelt 2019, Internship Report

<b>MahD</b>	Mahalanobian Distance
<b>MinD</b>	Minimum Distance
<b>MLC</b>	Maximum Likelihood Classification
<b>SVM</b>	Support Vector Machine
<b>NN_R</b>	Neural Network in R
<b>RF_R</b>	Random Forest in R
<b>SVM_R</b>	Support Vector Machine in R



## Optimal input data for classification

- depends on the available data
- difficulty to assess optimal choice grows with increasing number of parameters derived from the measurements
- airborne systems versus satellite systems

## Feature extraction

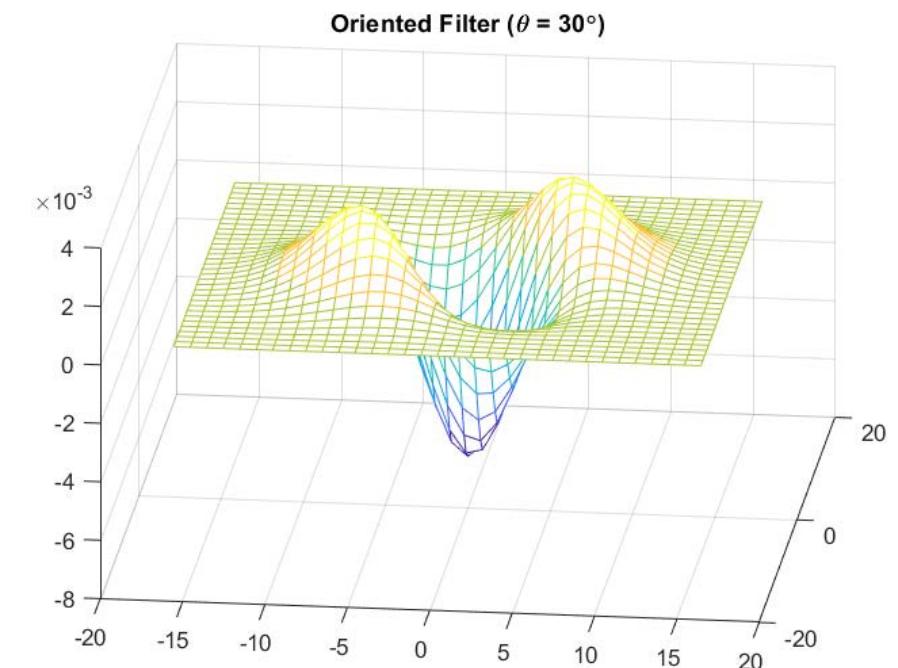
- special information required (e.g. ridges, icebergs)
- only a fraction of the image content is of interest
- how can this fraction be separated from the rest?

# Extracting ridges from coarse resolution SAR images (Markku)

- Goal: extract ridging information from operational SAR data.
- SAR images: EW Sentinel-1 images (40 m pixel, 90 m spatial resolution)
- Test sites: Baltic Sea, Kara Sea (future).
- Evaluation of results: using Radarsat-2 data combined with HEM data collected during the winter 2010-2011.

# Principles of the analysis

- Sign of the second derivative reveals if some location is a peak.
- 2-D directional filters which detect line fragments in different orientations.
- The theoretical foundation of the approach is presented in  
*Freeman and Adelson,  
The Design and Use of Steerable Filters,  
IEEE PAMI, 1991.*



# S1 EW 11 March 2016

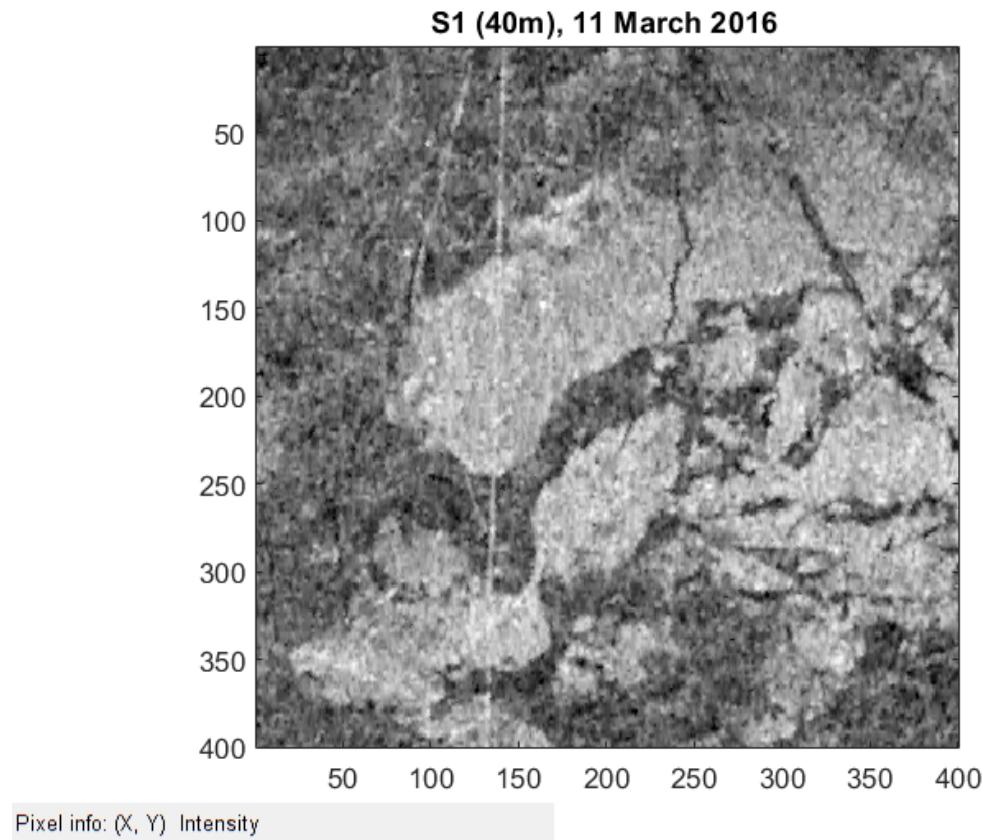
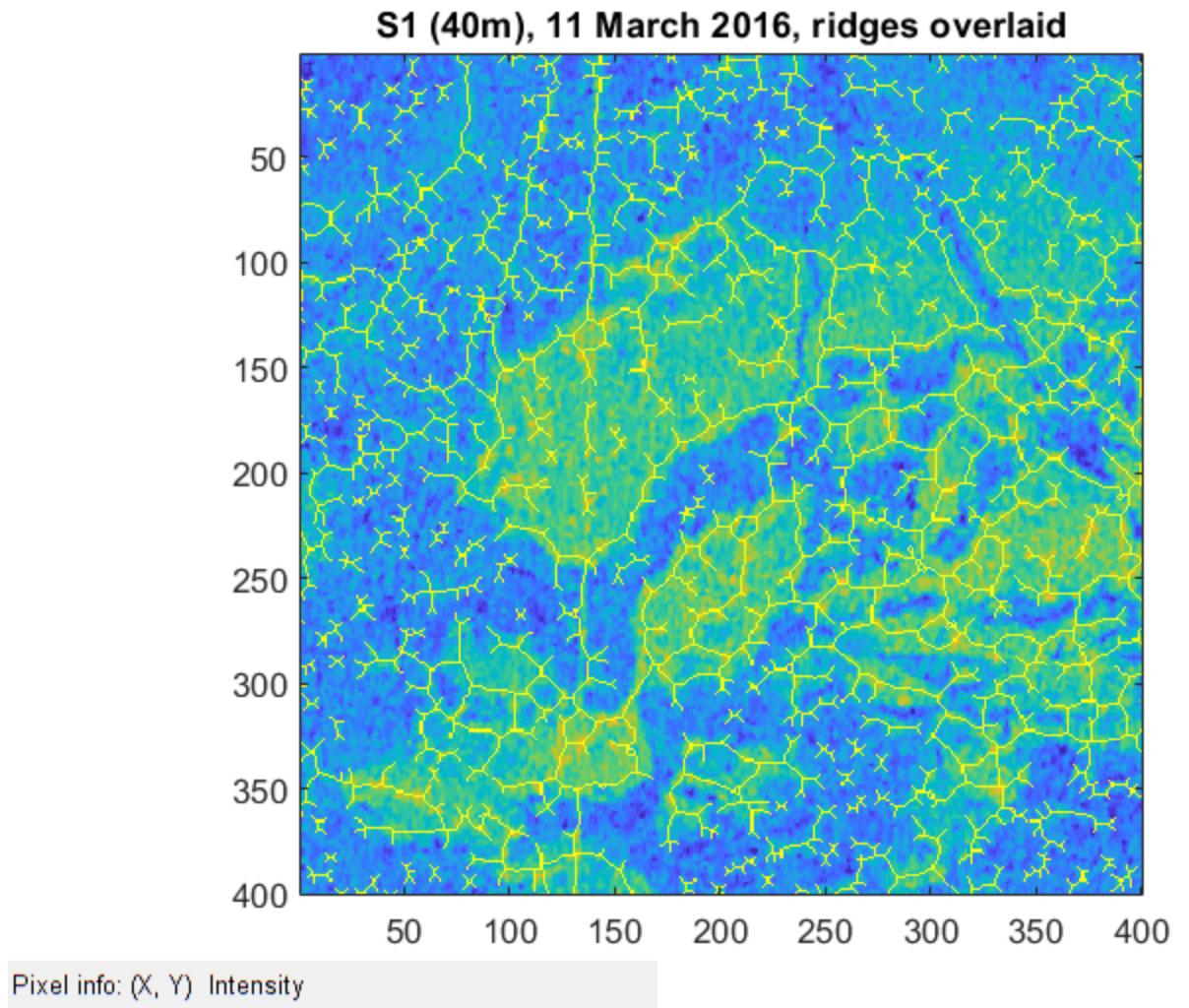


Image area 16 km by 16 km.

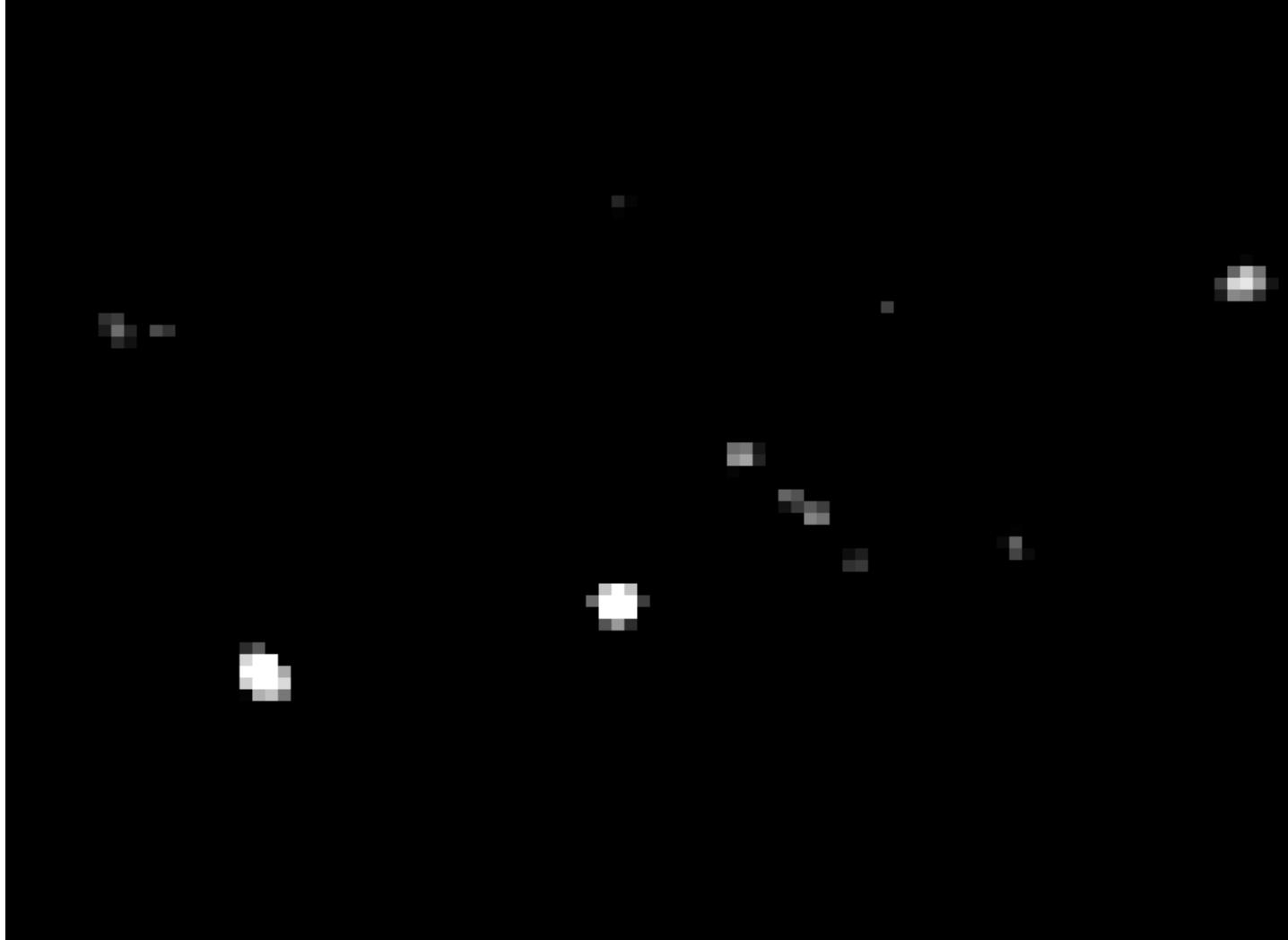


# Comments

- The approach generates several false alarms with a great likelihood .
- False ridge-like structures (e.g. brash ice channels created by ships) are hard to identify.
- Due to the coarse resolution a large fraction of ridges remain hidden.
- Which thresholds are optimal?



Soldal et al.  
Remote Sensing,  
2019



Soldal et al.  
Remote Sensing,  
2019

Also tested with  
S1-IWS mode

## Iceberg detection

- some icebergs identified in optical images cannot be seen in C-band SAR images!
- difficult detection in deformed ice and rough waters

## Iceberg detection

- wide coverage required (=> coarse resolution)
- icebergs can be small: growlers < 5m, bergy bits 5-15m, small bergs 15-60m, ... (=> high resolution)

## So: what did we learn?

- For operational use we have to find the best methods for ice mapping and feature extraction
- “Best” => criteria for selection?
- We know examples of good input parameters but do yet not know the optimal choice(s)
- => this may require to re-think strategies of data acquisitions (multi-frequency, multi-resolution,...)

## So: what did we learn?

- Urgently required: reference / validation data (mostly used until now: man-made ice charts)
- Possible scenario: (a) build-up of a free available data set consisting of different SAR and complementary data, (b) establishment of necessary criteria for algorithm selection, (c) multi-group approach to find the best algorithm